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Finite Element Modeling of Concrete Behavior at Early Age

Modelagem por Elementos Finitos do Comportamento do Concreto nas Primeiras Idades



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Abstract

In this work a computational model, based on the finite element method was implemented, to simulate the early age concrete behavior, having as a special feature, the evaluation of the cracking risk. The finite element analysis encloses the computational modeling of the following phenomena: chemical, thermal, diffusion and mechanical which occur at the first days after the concrete cast. The developed software results were compared with experimental values found in the literature, demonstrating an excellent agreement for all the implemented analysis.

Keywords: Concrete. Early age. Thermal analysis. Diffusion analysis. Mechanical Analysis.

Resumo

Neste trabalho é apresentado um modelo computacional, baseado no método dos elementos finitos, para a simulação do comportamento de peças de concreto nas primeiras idades, tendo, em especial, o propósito de avaliar o potencial risco de fissuração. A análise por elementos finitos abrange a modelagem computacional dos fenômenos químicos, térmicos, de difusão de umidade e mecânicos que ocorrem nos primeiros dias após o lançamento do concreto. Os resultados desta modelagem computacional foram comparados com valores experimentais encontrados na literatura, demonstrando excelente aproximação em todas as etapas de solução implementadas.

Palavras-chave: Concreto. Primeiras Idades. Análise Térmica. Análise de Difusão de Umidade. Análise Mecânica.

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1. Introduction

Over the past several years, many numerical tools have been developed to evaluate the measures adopted to reduce the cracking risk at early age (Lura, 2000; Morabito, 1998; Shah, 1994). These tools are based on mathematical models capable to describe the coupling of thermal, moisture diffusion, chemical and mechanical analysis.

In this work, according to Aurich (2008), a methodology for evaluate the potential cracking risk in concrete structures at early age is described. It will be shown numerical models to describe the main aspects of the chemical, thermal, moisture diffusion and mechanical phenomena that occur during the first days after the concrete cast and a computational implementation of these models through the finite element method.

In the chemical analysis, the heat released due to the exothermic reactions of the cement hydration is determined by a concrete adiabatic temperature rise curve. This heat released due to the temperature rise inside the body is the input for the next step.

In the thermal analysis, besides the heat released due to the exothermic reactions of the cement hydration, the heat flux on account of the difference of temperature between the body and the environment is considered. The nodal temperatures are evaluated from the body thermal and geometrical properties. These temperatures will be input data for the last step, the mechanical analysis.

The follow analysis is the moisture diffusion. Taking into account the similarity between the differential equation that governs the heat transfer analysis and the moisture diffusion, the same procedures used to evaluate the nodal temperatures in the previous step are used to determine the nodal values of relative pore humidity. These values will also be used as input data in the mechanical analysis.

In the mechanical analysis, the stress states due to the temperature and humidity changes evaluated in the previous steps and due to concrete shrinkage and creep are computed. When the stress state in any sample point reaches the failure surface, this point is considered cracked. The software considers concrete cracking through a smeared model with fixed crack.

The developed software results were compared with experimental values found in the literature, demonstrating an excellent approach for all the implemented analysis.



2. Chemical Analisys

In this analysis, the heat released due to the exothermic reactions of the cement hydration is determined by a concrete adiabatic temperature rise curve. In this study, the curve proposed by the Japan Society of Civil Engineers (JSCE, 1999), as shown in figure 1, or a curve determined from experimental data could be used.

According to JSCE (1999), the adiabatic temperature value, during the hydration reactions development, can be estimated according to equation 1.

$$\Delta T_{adiab} = \Delta T_{\max} \left(1 - e^{-1.25t} \right)$$
(1)

where:

• ΔT_{max} : maximum temperature achieved by cement in the calorimetric test;

t: time (between 0 and 70 days).

This analysis generates a volumetric load, in a perfect analogy with the structure self-weight, but instead of a force, it generates heat. This heat released due to the temperature rise inside the body is the input for the next step, the thermal analysis.

3. Thermal Analysis

According with Bathe (1996), for a heat transfer analysis in a twodimensional body, assuming that the material obeys the Fourier's Law of heat conduction, it can be written that:

$$q_x = -k_k \frac{\partial \theta}{\partial x} \qquad q_y = -k_y \frac{\partial \theta}{\partial y}$$
 (2)

where:

• q_x, q_y: heat flows conducted per unit area;

- θ: body temperature;
- + $\mathbf{k}_{\mathbf{x}},\,\mathbf{k}_{\mathbf{y}}$: thermal conductivities corresponding to the principal axes x,y.

Considering the heat flow equilibrium inside the body, it is obtained that:

$$\frac{\partial}{\partial x} \left(k_k \frac{\partial \theta}{\partial x} \right) + \frac{\partial}{\partial y} \left(k_y \frac{\partial \theta}{\partial y} \right) = -q^B$$
(3)

where q^B is the rate of heat generated per unit volume.

On the surface of the body, the following conditions must be satisfied:

$$\Theta|_{S_{\Theta}} = \Theta^{S}$$
(4)



where:

- θ^{s} : known temperature at the surface S_{θ} ;
- k thermal conductivity of the body;
- n: unit normal vector to the surface of the body;
- q^s: prescribed heat flux input on the body surface S_a.

Three boundary conditions may be considered in the heat transfer analysis:

- Temperature conditions: the temperature may be prescribed or fixed on certain points or surfaces of the body, denoted by S_a in equation 4;
- Heat flow conditions: the heat flow input may be prescribed in certain points or surfaces of the body. These heat flow boundary conditions S_a are specified in equation 5;
- Convection boundary conditions: the convection may be included as boundary condition, adding the following term in equation 5:

$$q^{s} = h\left(\theta_{e} - \theta^{s}\right)$$
(6)

where h is the convection coefficient. Here at environmental temperature θ_{e} is known, but the surface temperature θ_{s} is unknown. For the finite element solution of the heat transfer problem, using the principle of virtual temperatures, given as:

$$\int_{V} \overline{\Theta}^{T} k \Theta^{'} dV = \int_{V} \overline{\Theta} q^{B} dV + \int_{Sq} \overline{\Theta}^{S} q^{S} dS + \sum_{i} \overline{\Theta}^{i} Q^{i}$$
(7)

where:

$$\Theta^{T} = \begin{bmatrix} \frac{\delta \theta}{\delta x} & \frac{\delta \theta}{\delta y} \end{bmatrix}$$
(8)

$$k = \begin{bmatrix} k_x & 0\\ 0 & k_y \end{bmatrix}$$
(9)

and Qⁱ is the concentrated heat flow input. Each Qⁱ is equivalent to a surface heat flow, over a very small area. The bar over the temperature θ indicates that a virtual temperature distribution is being considered.

In the heat transfer problem considered above only it is assumed steady state conditions. However, when significant heat flow input changes are specified over a short time period (due to a change of any boundary conditions or the heat generation in the body), it is important to include a term that takes account of the rate at which heat is stored within the material. The rate of heat absorption may be considered as:



where c is the material specific heat capacity. The variable q^c can be understood as a part of the heat generated, which must be subtracted from the otherwise generated heat q^B in the expression 7. This effect leads to a transient response solution.

4. Moisture Diffusion Analysis

In the diffusion most general case, according to CEB-FIP Model Code 1990 (1993), Kwon (2008) and Jeon (2008), gases, liquids and solutions are transported, through a porous medium, according with the Fick's First Law of Diffusion, considering a transient phenomenon, such as drying of the concrete, the balance equation is given by:

$$\frac{\partial H}{\partial t} = \frac{\partial}{\partial x} \left(D(H) \frac{\partial H}{\partial x} \right)$$
(11)

where:

- D(H): diffusion coefficient (m²/s) at relative pore humidity H dH
- $\frac{dx^2}{dx}$: gradient in relative pore humidity (m⁻¹)

A study conducted by Baluch (2008) established an analogy between the heat transfer analysis and the moisture diffusion inside of a concrete body

The differential equation that governs the heat transfer phenomenon, in the transient solution, can be written as.

$$\frac{\partial \theta}{\partial t} = \frac{k}{\rho c} \left(\frac{\partial^2 \theta}{\partial x^2} + \frac{\partial^2 \theta}{\partial y^2} \right)$$
(12)

where:

• $\theta = \theta(x, y, t)$: temperature as a function of location variables x and y and the time variable t;

- k: thermal conductivity;
- c: specific heat;
- ρ: density.

Similarly, rewriting the differential equation that governs the moisture diffusion phenomenon, it is transformed to:

$$\frac{\partial H}{\partial t} = D(H) \left(\frac{\partial^2 H}{\partial x^2} + \frac{\partial^2 H}{\partial y^2} \right)$$
(13)

where:

• H = H (x, y, t): pore relative humidity as a function location variables x and y and the time variable t;

• D(H): moisture diffusion coefficient (usually as a function of H). Considering the boundary conditions in the heat transfer analysis, it can be written that:

$$\frac{\partial \Theta}{\partial n} = h \left(\Theta_e - \Theta^S \right)$$
 (14)

where:

• $\frac{\partial \theta}{\partial n}$: thermal gradient at the surface;

- h: convective coefficient;
- θ_{a} : temperature at the surface of the solid;
- θ^{s} : temperature of the ambient space.

Also, considering the boundary conditions in the moisture diffusion analysis, it can be written that:

$$D(H)\frac{\partial H}{\partial n} = \alpha_m \left(H_e - H^s\right)$$
(15)

where:

• $\frac{\partial H}{\partial n}$: moisture gradient at the surface;

- α_m: mass transfer factor;
- H : relative pore humidity at the surface of the porous medium;
- H^s: relative humidity of the ambient space.

Comparing the equations that describe the moisture diffusion and heat transfer analysis, it is clear that exists an analogy between both problems. The correspondence between the parameters in the analyses can be seen in table 1.

5. Mechanical Analysis

Finite elements for axis-symmetrical, plane stress and strain analy-

Table 1 - Corresponding terms in the differentialequations for moisture diffusionand heat transfer (Baluch, 2008)					
Heat transfer		Moisture diffusion			
θ (x, y, †)	\leftrightarrow	H (x, y, †)			
k ρc	\leftrightarrow	D(H)			
h	\leftrightarrow	$\boldsymbol{\theta}_{m}$			
θ_{e}	\leftrightarrow	H _e			
θ_{s}	\leftrightarrow	H^{s}			

ses have been implemented. According to figure 2, the concrete is represented through a viscoelastic model, corresponding to a chain composed by five Maxwell's elements in parallel. Bazant and Wu (1974) presented an algorithm to automatically determinate the parameters E_{μ} (t) and η_{μ} (t) for each age, t, of concrete, from experimental results or standard concrete values. According to Aurich (2008) this model is calibrated from the creep formulation presented in Código Modelo CEB-FIP Model Code 1990 (1993) or FIB (1999).

The concrete shrinkage and thermal expansion strains are considered as prescribed deformations on structure. As creep, concrete shrinkage strains are evaluated according to CEB-FIP Model Code 1990 (1993) or FIB (1999), which considers different expressions to determinate the autogenous and the drying shrinkage.

The failure criterion proposed by Ottosen (1977) is adopted to identify concrete cracking. Figures 3a and 3b show the meridians and the cross sections of this failure surface.

This failure criterion was adopted by CEB-FIP Model Code 1990 (1993) and is expressed by:

$$\alpha \frac{J_2}{f_{cm}^2} + \lambda \frac{\sqrt{J_2}}{f_{cm}} + \beta \frac{I_1}{f_{cm}} - 1 = 0$$
 (16)

where $\boldsymbol{f}_{_{\!C\!M}}$ is the mean value of concrete compressive strength, and,



$$\lambda = c_1 \cos[1/3 \arccos(-c_2 \sin 3\theta)], \text{ for } \sin 3\theta \le 0$$

$$\lambda = c_1 \cos[\pi/3 - 1/3 \arccos(c_2 \sin 3\theta)], \text{ for } \sin 3\theta > 0$$

$$\sin 3\theta = -\frac{3\sqrt{3}}{2} \frac{J_3}{J_2^{3/2}}$$
(18)

where,

• I1: first invariant of stress tensor;

• J_2 , J_3 : the second and the third invariant of deviatoric stress tensor. The concrete stress-strain behavior of concrete subjected to tensile stresses should be expressed by two relations: a stress-strain relationship representing the behavior of the concrete outside the fracture zone and a stress-crack opening relation which describes the deformations occurring within the fracture zone.

The CEB-FIP Model Code 1990 (1993) presents a stress-crack opening relation for cracked concrete, σ -w, as shown in figure 4. To represent the uncracked concrete behavior, subjected to tensile stresses, the CEB-FIP Model Code 1990 (1993) suggests a bilinear stress-strain relationship, as given in equations 19 and 20:

for $\sigma \le 0.9 f_{ctm}$:

$$\boldsymbol{\sigma}_{ct} = \boldsymbol{E}_c \cdot \boldsymbol{\varepsilon}_{ct}$$
 (19)

■ for $0.9f_{ctm} \le \sigma_{ct} \le f_{ctm}$:

$$\sigma_{ct} = f_{ctm} - \frac{0.1 f_{ctm}}{0.00015 - \frac{0.9 f_{ctm}}{E_c}} (0.00015 - \varepsilon_{ct})$$
(20)

where:

• E_c: tangent modulus of elasticity (MPa);



- f_{ctm} : tensile strength; σ_{ct} : tensile stress (MPa);
- ε_{ct}: tensile strain.

Equations 21 to 24 describe the bilinear stress-crack opening relation, which evaluates strain in cracked concrete: for: $0.15 f_{ctm} \le \sigma_{ct} \le f_{ctm}$

$$\sigma_{ct} = f_{ctn} \left(1 - 0.85 \frac{w}{w_1} \right)$$
(21)

for: $0 \le \sigma_{ct} \le 0.15 f_{ctm}$:

$$\sigma_{ct} = \frac{0.15 f_{ctn}}{w_c - w_1} (w_c - w)$$
(22)

$$w_1 = 2\frac{G_F}{f_{ctm}} - 0.15 w_c$$
 (23)

$$w_c = \beta_F \frac{G_F}{f_{ctm}}$$
(24)

where:

- w₁: crack opening (mm);
- w_c : crack opening for $\sigma_{ct} = 0$;

• G_{F}^{c} : fracture energy (Nm/m²); • β_{F}^{c} : coefficient that depends on the maximum aggregate size as given in table 2.

The fracture energy, G_F, can be calculated as:

$$G_F = \alpha_F \left(\frac{f_{ctm}}{10}\right)^{0.7}$$
(25)

where α_{E} is a coefficient that depends on the maximum aggregate size, also given in table 2.

Numerical Applications 6.

Numerical applications of the described methodologies throughout

Table 2 – Coefficients $\alpha_{\mbox{\tiny F}}$ and $\beta_{\mbox{\tiny F}}$				
d _{max} (mm)	α _F	β _F		
8	0.02	8		
16	0.03	7		
32	0.05	5		



this work are presented in this item. The experimental results of concrete rings tests will be compared with the developed software results for the time at which the cracks occur and the increase of the crack opening.

Grzybowski and Shah (1990) developed a test using a ring specimen to study the concrete cracking with restrained shrinkage. The test consists in a concrete ring internally limited by a steel ring, in which are placed strain-gages for strain measuring, and an external microscope to measure the crack width. The tests proposed by the authors were conducted at ACBM laboratory (Center for Advanced Cement-Based Materials at Northwestern University, Evanston, Illinois) with the purpose to compare different types of shrinkage-reducing admixtures performances at early age. The dimensions of the specimens are given in figure 5.

The specimens were cured for 4 hours at 20°C and 100% RH, and

then after demoulding exposed to drying in the humidity room at the ambient temperature of 20°C and 40% RH.

Figure 6 illustrates the test, the position of the strain-gages in the steel rings and concrete ring prepared for testing.

To analysis the algorithm results, this paper studies two rings tested by Shah, Karaguler and Sarigaphuti (1993) and Shah *et al* (1994). The results for temperature rising, moisture diffusion and stress development are presented. The comparison between the results for the time at which the cracks occur and the increase of the crack width is also showed.

The mesh used for the finite element analysis has 168 elements and can be seen in figure 7.

The boundary conditions adopted for the axis-symmetrical analysis (thermal, diffusion and mechanical) are shown in figures 8, 9 and 10.

The parameters considered in the thermal, moisture diffusion and





mechanical analysis for both studied rings are shown in tables 3, 4 e 5.

Figure 11 shows the temperature rising for two nodes, P1, situated in the central zone of the concrete ring, and P2, situated in the external surface of the concrete ring.

The temperature development maps are shown in figure 12. It can





be seen that the maximum temperatures, due to the heat generated by the cement hydration reactions, occur in the central zone of the concrete ring. This situation was already verified in figure 11, where the node P1, situated in the central zone of the concrete ring, reached a higher temperature than the node P2, situated in the external surface of the concrete ring. In the fifth day, the concrete ring temperature had already equalized with the environment temperature.

Figure 13 shows the moisture diffusion development for two nodes, P1, situated in the central zone of the concrete ring, and P2, situated in the external surface of the concrete ring. The moisture dif-



fusion development maps are shown in figure 14. It can be seen that the drying process, due to the environmental relative humidity is lesser than the initial relative humidity of the concrete ring, occur form the external surface to the central zone of the concrete ring. This situation was already verified in figure 13.

The mechanical analysis results are shown for both rings tested, which properties were observed in table 5. The ring 2 (Shah, Karaguler and Sarigaphuti, 1993) were made with a concrete which compressive strength and Young modulus higher than ring 1 (Shah *et al*, 1994).

Figure 15 shows, for ring 1 (Shah *et al*, 1994), the comparison between experimental and numerical results for the time at which

Table 3 – Materials Thermal Properties				
Properties	Concrete	Steel		
Thermal Conductivity	0.33	45.55		
(kJ/cm.day.°C)	2,00			
Convection Coefficient	0.10	-		
(kJ/cm².day.°C)	0.12			
Thermal Capacity	1 1 4	0.419		
(kJ/cm³.day)	1,10			

Table 4 – Materials Diffusion Properties			
Properties	Concrete	Steel	
Diffusion Coefficient (m²/s)	0.06048	1,10°	
Mass Transfer Factor	3.33	-	

Table 5 – Materials Mechanical Properties				
Properties	Concrete	Steel		
Young Modulus	2,500 (ring 1)	20.000		
(kN/cm²)	3,500 (ring 2)	20,000		
Poisson Ratio	0.2	0.3		
Compressive Strength (28 days)	3.034 (ring 1)	_		
(kN/cm²)	3,556 (ring 2)			



the cracks occur and the increase of the crack width. Figure 16 shows the same comparisons for ring 2 (Shah, Karaguler and Sarigaphuti, 1993).

The stresses development maps for ring 1 (Shah *et al*, 1994) are shown in figure 17. In these maps it could be observed that the crack opening occurs from the external surface to the interior of the concrete ring, to support what was observed in the test, according to figure 18.

The agreement between the numerical and experimental results, for the time at which the crack occurs and the increase of the crack width, is excellent. The numerical analysis shows why ring 2, with higher strength, cracks earlier than ring 1. The concrete shrinkage prescribed deformations generate stresses proportional to Young modulus, and the tensile strength development at early age is not enough to avoid the cracking formation in the stiffener ring.

It can be seen that, in the stresses development maps showed in figure 17, in the tenth day the red color appears in the external surface of the ring. This color corresponds to the stress level equivalent to the concrete tensile strength. So, the crack opens on the external surface, reducing the stress value. At the fourteenth day, the red stress level is reached again in a further internal position (the stress on external surface is close to zero). In sequence, with the crack propagation, the stress level falls down. At the nineteenth day, the stress peak is reached in a more internal position, being followed by the stress reducing. This circumstance successively repeats each time closer to the steel ring surface.

7. Conclusions

The results achieved, even considering the concrete behavior inherent variability, demonstrated that the adopted models could simulate the actual concrete behavior at early age. The implemented finite element model proved to be an accurate and appropriate tool to predict the concrete cracking in different concrete structures.



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Figure 16 – Crack width for ring 2 (Shah, Karaguler and Sarigaphuti, 1993)





