

## PHYSICAL CONNECTION BETWEEN BVRF SEGMENTS BASED ON LEVELING ASSOCIATED WITH GRAVIMETRY

### *Conexão física entre segmentos da RVRB com base em nivelamento associado a gravimetria*

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Received in September 06<sup>st</sup> 2018

Accepted in December 20<sup>th</sup> 2018

#### **Abstract:**

Considering the efforts to establish Global Reference Systems linked to the geopotential space, new alternatives are sought to address the problems found in the classic national vertical networks. The Brazilian Vertical Reference Frame (BVRF) was materialized in two different segments with independent datums (Imbituba and Santana tide gauges) due to the terrain difficulties for conventional leveling. The 2018 BVRF realization, in the geopotential space, still remains without interoperability between its segments. We analyze alternatives for physical connection based on the new precepts of the International Association of Geodesy (IAG) involving the geopotential space. Some proposed solutions for physical connection based on GPS leveling associated with gravimetry are presented. These solutions were developed with the aim of evidencing the discrepancy between the two BVRF segments, now carried out in terms of geopotential numbers and normal heights. The results indicate differences ranging from about 45 cm to 140 cm between the two segments depending on the strategy employed. Comparisons with previous determinations based on indirect strategies and involving previous BVRF realizations are made.

**Keywords:** Geopotential Space; Geopotential level differences; Normal heights; Geopotential Numbers; BVRF.



**Resumo:**

Considerando os esforços no estabelecimento de Sistemas de Referência Globais vinculados ao geopotencial, buscaram-se novas alternativas para abordar os problemas apresentados nas redes verticais clássicas nacionais. A Rede Vertical de Referência do Brasil (RVRB) foi materializada em dois segmentos distintos, com origens independentes (marégrafos de Imbituba e Santana), devido às dificuldades do terreno para métodos convencionais de nivelamento. A realização 2018 da RVRB, no espaço do geopotencial, ainda permanece sem interoperabilidade entre seus segmentos. Com estes antecedentes investigam-se alternativas para conexão física com base nos novos preceitos da *International Association of Geodesy* (IAG), envolvendo o espaço do geopotencial. Algumas soluções referentes à conexão física baseadas em nivelamento com GPS associado com gravimetria são apresentadas. As soluções foram desenvolvidas buscando evidenciar a discrepância entre os dois segmentos da RVRB ora realizada em termos de números geopotenciais e altitudes normais. Os resultados apontam diferenças variando de 45 cm a 140 cm entre os dois segmentos dependendo das estratégias empregadas. São apresentadas comparações com determinações indiretas das discrepâncias, efetivadas anteriormente e relacionadas com realizações prévias da RVRB.

**Palavras-chave:** Espaço do Geopotencial; desníveis geopotenciais; Altitudes Normais; Números Geopotenciais; RVRB.

## 1. Introduction

Earth System change monitoring activities demand accuracy and reliability in realized spatial position referencing. The requirements for quantifying the dynamical process within the planet are strongly dependent on modeling the mass flux inside the Earth's System based on changes in its geometry, rotation and gravity field (Kutterer, Neilan, and Bianco 2012). In this sense, the quality of Geodetic Reference Systems (GRS), involving positions, gravity, and geodynamical aspects, must support accuracy requirements tending to 1 ppb in the forthcoming years (Plag et al. 2009). These aspects refer to the main present challenges in the global Geodesy.

Considering the need for an effective Earth Observing System for monitoring global changes, in 2003 the International Association of Geodesy (IAG) established the Global Geodetic Observing System (GGOS) as a central element for integrating all global geodetic infrastructure composed by systems involved at diverse levels of observation, conventions, databases, and models as well as new geodetic methods and services. GGOS Theme 1 - Global Unified Height System - was established in 2010 as a fundamental element for integrating geometry and gravity field aspects. These aspects were reinforced by United Nations General Assembly Resolution A/RES/69/266 in February 2015. This resolution established "A Global Geodetic Reference Frame for Sustainable Development", within the "United Nations Global Geospatial Information Management (UN-GGIM)" by recognizing the coordinated approach of IAG with regard to GGOS. IAG Resolution 1/2015 defined the International Height Reference System (IHRS) with the meaning of a global equipotential surface as a common global vertical reference with geopotential value  $W_0 = 62\,636\,853.4 \text{ m}^2\text{s}^{-2}$  and the geopotential number  $C_P = W_0 - W_P$ , as the primary vertical coordinate (IAG 2015a). IAG Resolution 2/2015 related to the "Global Absolute Gravity Reference System" (GAGRS) intended to replace the "International Gravity Standardization Net 1971 - IGSN71" (IAG 2015b). As a consequence of this, the Global Geodetic Reference System (GGRS) and

its realization (GGRF) were defined, where each point P is described by its geometric coordinate vector  $\vec{X}_P$  ( $X, Y, Z$ ) referring to the space-oriented Earth involved in the realization of the International Terrestrial Reference System (ITRS), and also by the geopotential  $W_P$ , the physical height  $H(C_P)$ , and the gravity vector  $\vec{g}$  involved in IHRS. GGRS thus includes the geometry, gravity field, and the Earth's orientation in space (IAG 2016).

Several efforts are currently underway for realizing the global IHRS (IHRF) frame. There are still several limitations for establishing IHRF, such as heterogeneities in standards for realizing National Vertical Reference Systems (NVRS) and the lack of geodetic information with adequate metadata for supporting the solution of the Geodetic Boundary Value Problem (GBVP) independent of local reference frames and with qualification of data and elimination of outliers (Santacruz and De Freitas. 2015). These backgrounds are fundamental for the determination of geopotential numbers with a minimum accuracy of  $1 \times 10^{-2} \text{ m}^2 \text{ s}^{-2}$  coherent with IHRS and GGOS purposes (Drewes et al. 2016).

The coordination of activities related to the IHRS realization is done by the "IAG/GGOS WG 0.1.2 on the Strategy for the Realization of the IHRS" in which the SIRGAS Working Group III (Vertical Datum) takes part. In this context the following SIRGAS WGIII protocols are distributed to member countries:

- Strategies for the establishment of vertical networks by physical heights [ $H_P = f(C_P)$ ];
- Link of national vertical networks to the SIRGAS GNSS Continuous Stations;
- Integration of national vertical networks of members countries in the geopotential space;
- Approaches for referring the SIRGAS Vertical Frame to the  $W_0$  value of IHRS;
- Association to a specific epoch by considering the realization epoch and temporal variations in coordinates;
- Planning of activities for establishing a GGRF/IHRF station profile in the SIRGAS region.

Argentina, Brazil, and Uruguay achieved partial relevant results related to the SIRGAS WG III protocols by realizing their NVRS in the geopotential space although still linked to local Vertical Datums. However, several problems remain when IHRS standards are considered.

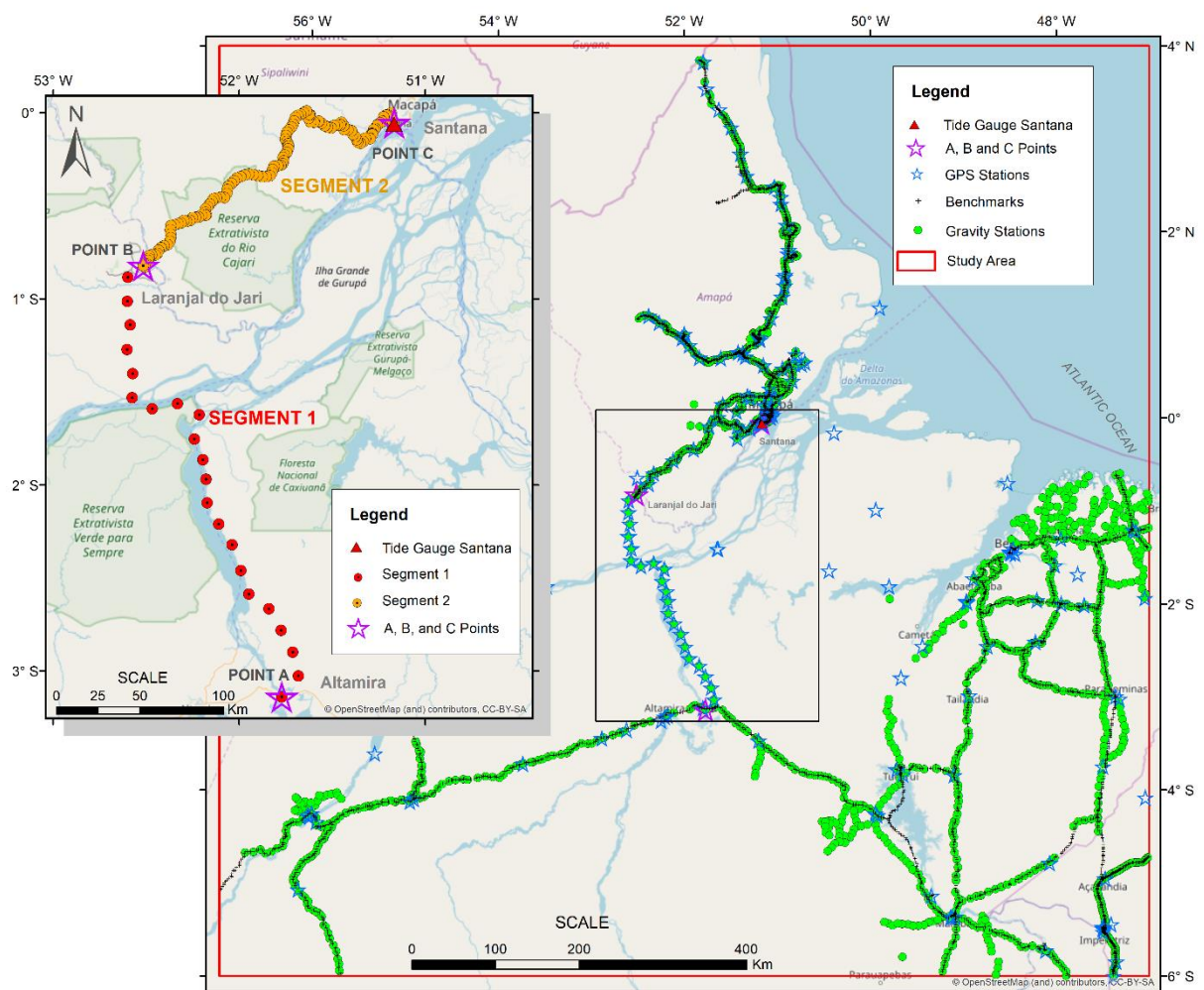
The Brazilian Geographic and Statistics Institute (IBGE) is working to surpass some structural problems for modernizing the Brazilian Vertical Reference Frame (BVERF). One of these problems is related to the realization of the network in two different segments. Most benchmarks are linked to the southern Brazilian Vertical Datum of the Imbituba tide gauge (BVD – I) and about five percent of stations are linked to the northern Vertical Datum of the Santana tide gauge (BVD – S). It is almost impossible to link the two segments by conventional spirit leveling because of the difficulties in surpassing the Amazon River mouth and large inaccessible portions of the Amazon Rainforest involving distances over three hundred kilometers of inaccessible wet regions.

The studies conducted described in this manuscript aim to provide solutions to several problems based on data coming from different modern geodetic techniques. A fundamental step is to restrict data to the same Geodetic Reference System and permanent tide System. These conditions are essential in order to observe the interoperability condition. The reference frames mentioned above are followed in this work and it is in accordance with IAG recommendations for realizing IHRS and for modernizing NVRS (Sánchez et al. 2017; Sánchez and Sideris 2017).

IBGE's strategies and current activities in cooperation with the Federal University of Paraná (UFPR) for solving the connections between the two BVRF segments in the geopotential space and the results obtained are presented in this paper.

## 2. Amazonian Connection Area and description of involved Database

During the course of the historical cooperation between IBGE and UFPR related to BVRF modernization (De Freitas, Ferreira, and Luz 2018), an area  $10^{\circ} \times 10^{\circ}$  was delimited in the Amazonian region involving the states of Amapá and Pará with the aim of establishing a physical connection between the two BVRF segments (Fig. 1). New strategies for leveling associated with gravimetry were considered.



**Figure 1:** Connection Area, existing Data and new Surveys between the segments linked to BVD – I and BVD – S (referred to the BVRF).

In order to enable a better understanding, the data set was divided into two segments as per Figure 1 and Table 1.

**Table 1:** Details of the segments

	Leveled Segment 1	Leveled Segment 2
Reference	From point A to point B	From point C to point B
Number of leveled points	23	131
Vertical Datum	Imbituba (IMBT)	Santana (SANT)
Involved Data	$(\varphi, \lambda, h, g_{obs})$	$(\varphi, \lambda, \Delta n, g_{obs})$
Source of Data	GPS + Gravimetry	Spirit Leveling + GPS + Gravimetry
Distance Involved	269.254 km	172.428 km

Table 2 shows specific information relating to the initial points of the leveled segments.

**Table 2:** Information relating to the initial points of the leveled segments

	Point A	Point B	Point C
Place	Altamira	Laranjal do Jari	Santana
Latitude	-3° 8' 20.3788"	-0° 49' 19.0841"	-0° 3' 16.0643"
Longitude	-51° 46' 16.8785"	-52° 30' 56.3711"	-51° 10' 2.1606"
GPS Station #	96284	99500	99619
BM name	BM104	5006J	4027E
Gravity Station #	8123121	8122995	8078214

Figures 2 and 3 present the reference surfaces of the initial points of the leveled segments by considering the geoid height as well as height anomaly computed from the Global Geopotential Model (MGG) XGM2016 (Pail et al. 2016) in its maximum degree and order (d/o). We justify the use of this model because of its performance in the region, even considering its medium resolution (Nicacio, Dalazoana and De Freitas 2018).

IBGE's Geodesy Coordination carried out the surveys related to the two connection segments mentioned. In segment 1 (A – B in Fig. 1), which relates to BVD – I conventional spirit leveling is impossible. The survey of level differences in this segment was therefore carried out based on GPS and gravimetry along a stretch of about 269 km, considering the maximum distance of 15 km between two neighboring GPS stations because of the uneven characteristics of region involved and requirements for gravity frequency measurements at 10 km to 15 km intervals in undulating topography regions according to Ramsayer (1963) and De Freitas and Blitzkow (1999). Spirit leveling associated with gravimetry and sparse GPS positioning was realized along about 172 km of segment 2 which is linked to the BVD - S. Besides the densification of geodetic observations in the region, this new set of information was established with the aim of improving some studies on connecting the Santana and Imbituba BVD conducted by LARAS (Laboratory of Geodetic Reference Systems and Satellite Altimetry of UFPR). These studies are described in Montecino and De Freitas (2014), Moreira and De Freitas (2016) and De Freitas et al. (2016). These previous works were based on the least square estimation of differences between modeled height anomalies, and

GPS/Lev. differences. Spectral decomposition, Global Geopotential Models (GGMs) enhancement and RTM were applied without observing true physical level differences. The results are synthesized in Table (3) which already includes corrections to previous different BVRF realizations with the aim of making them compatible with the 2018 BVRF realization.

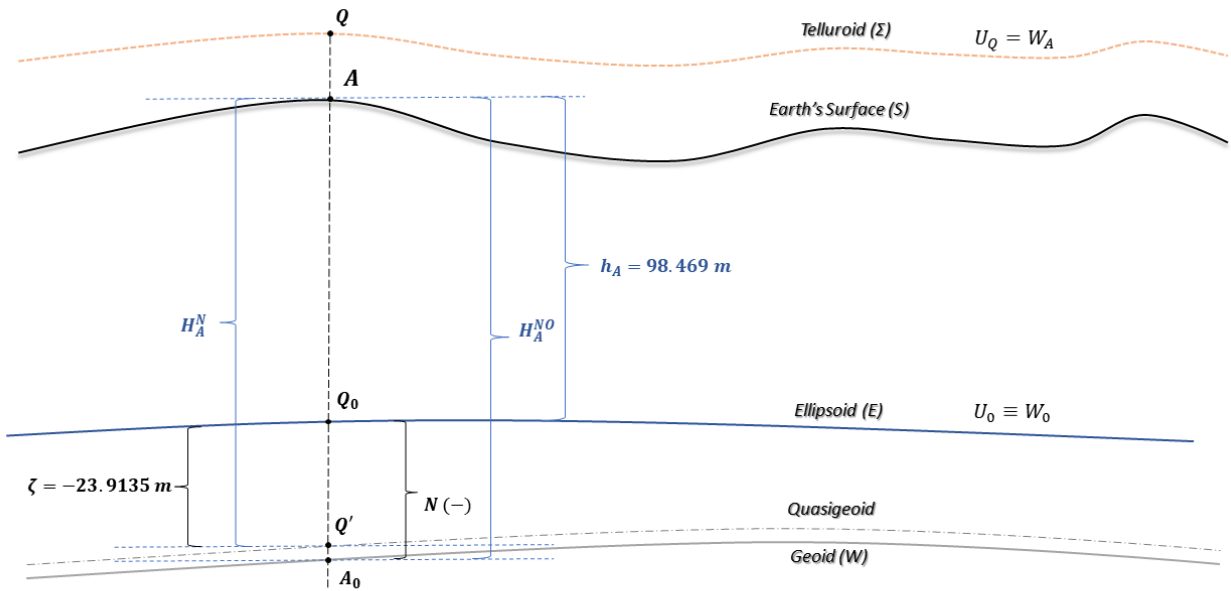


Figure without scale

Figure 2: Point A position and related physical and geometric reference surfaces.

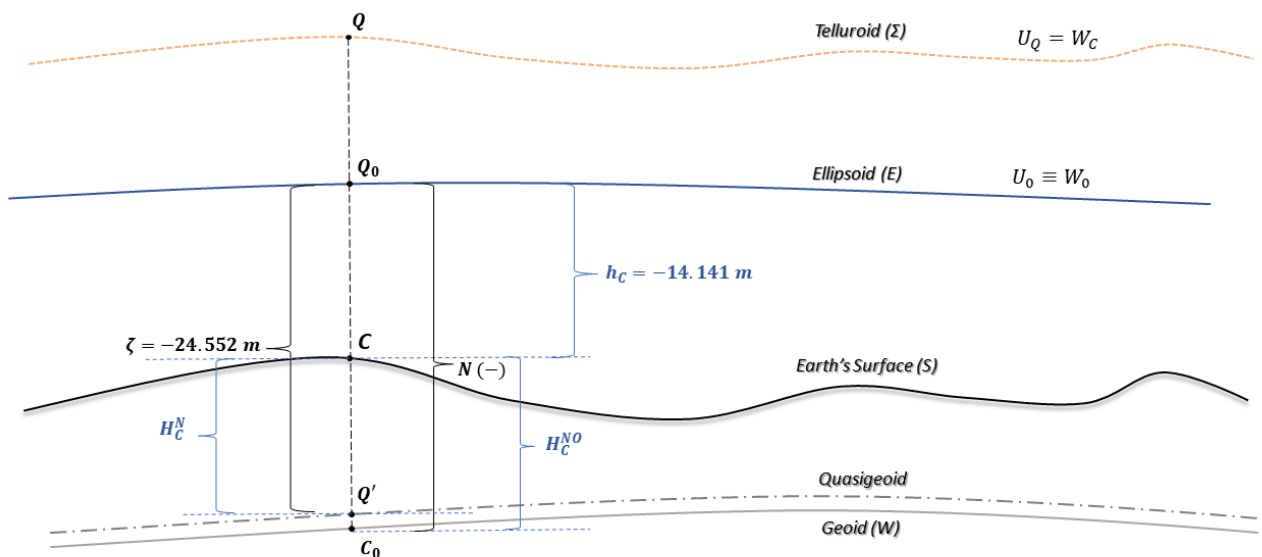


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Figure 3: Point C position and related physical and geometric reference surfaces.

**Table 3:** Different computed offsets between BVD-I and BVD-S

Previous studies: SANTANA above IMBITUBA				
Authors	Year of Study Completion	Offset (m)	BVRF Realization	Method
Montecino & De Freitas	2014	1.354( $\pm$ 0.59m) *	RAAP/AAGP(1992)	LSA+GGMs+RTM
Moreira & De Freitas	2016	1.084( $\pm$ 0.21m) **	RAAP/2011	LSA+GGM+ $\eta$
De Freitas et al.	2016	1.200( $\pm$ 0.21m) **	RAAP/2011	Mixed LSA and GGMs

\* The offset calculated by Montecino and De Freitas (2014) considering a solution involving GOCE+EGM2008+RTM is 1.420 m ( $\pm$ 0.56m). This offset shows that the Imbituba datum is located below the Santana datum. This offset value took into consideration the discrepancy of 0.15 m at point A (Fig. 1) between AAGP (*Ajustamento Altimétrico Global Preliminar* – Preliminary Global Altimetric Adjustment) and the 2011 adjustment (IBGE 2011 pp. 52), and also the difference of -0.216 m between the 2011 and 2018 adjustments (IBGE 2018, pp. 35). There is no control over the error estimation of heights related to AAGP in the region. We then propagated only the error estimation of about  $\pm$ 0.14 m around point A from the 2011 adjustment (IBGE 2011, pp. 50) and that from the 2018 adjustment ( $\pm$ 0.11 m) according to IBGE (2018 pp. 34) even considering that there is a discrepancy involved between AAGP and the 2011 adjustment.

\*\* The offset calculated by Moreira and De Freitas (2016) is 1.30 m ( $\pm$ 0.11 m) and that calculated by De Freitas et al. (2016) is 1.416 m ( $\pm$ 0.12 m). These values took into consideration the difference of -0.216 m at point A between the 2011 and 2018 BVRF realizations. The error estimation of the adjusted heights in the point A region relating to 2011 and 2018 adjustments was propagated for both solutions.

## 2.1 Database Analysis

The data obtained for heights and gravity from the two leveled segments were pre-analyzed as to their consistency. Several actions were necessary for correcting above all changes of nomination, duplicity, and several inconsistencies related to different numerical forms for expressing the same kind of measurements (e.g. owing to lack of significative numbers). Analyses were also performed based on GGMs with the aim of detecting possible outliers because of the complex characteristics of the area involved and new techniques employed. It was also necessary to qualify previously available data in several different databases relating to different reference frames and epoch. All the data obtained were reduced to the mean permanent tide system (see e.g. Tenzer et al. 2011).

With regard to segment 1, the GPS survey results of 23 points, the associated gravity observations and the normal height of the initial point were analyzed. It must be emphasized that initial point A is not part of the official BVRF because of the large destruction of BMs in the region. The starting point used (BM104, Table 2) is a second order point derived from the 2011 BVRF.

In segment 2 it was necessary to recover raw leveling differences referring to BVD – S and in some cases to interpolated gravity information for computing geopotential number differences with a severe discrimination of wrong information.

### 3. Methodology and Results

In accordance with the conventions for IHRS established in IAG Resolution 1/2015 (IAG 2015a), the global reference zero level is that associated with the equipotential surface with the conventional value  $W_0 = 62\,636\,853,4 \text{ m}^2\text{s}^{-2}$  (Sánchez et al. 2016). In this system, the primary vertical coordinates of a point P with geopotential  $W_P$  is the geopotential number, already referred in the Introduction, given by (more details in Hofmann-Wellenhof and Moritz 2005, pp. 55):

$$C_P = W_0 - W_P \quad (1)$$

Considering a particular NVRS, the geopotential number refers to the particular equipotential surface  $W_{0i}$  and is given by:

$$C_{P_i} = W_{0_i} - W_P = \int_{0_i}^P g dn \cong \sum g_{mj} \Delta n_j \quad (2)$$

Where the geopotential number can be computed with sufficient approximation by the sum of the products of the mean gravity  $g_m$  value in a leveling section and the observed level differences  $\Delta n$  if the leveling section is not too large (see practical conditions e.g. in De Freitas and Blitzkow 1999). Because the characteristics of the two segments of leveling used in the connection are quite different (GPS + gravimetry in segment 1 and spirit leveling + gravimetry + sparse GPS in segment 2) some strategies were developed for testing the approach used. In segment 1 the ellipsoidal height differences and gravity measurements were considered as the main subject while the raw spirit leveling differences associated with gravity values in each section were the main subject in segment 2. Different solutions were employed for each segment as set out in the following section.

#### 3.1 Strategies for computing normal heights and geopotential numbers.

The leveling line of each segment started from a point where normal height was determined. At starting point A (BM104, Table 2) of leveling segment 1, a discrepancy of about -216 mm was considered between the normal heights in the 2018 BVRF adjustment and the normal-orthometric height in the 2011 adjustment. The reason is that in the region around point A the interval of the discrepancy detected by the 2018 BVRF adjustment, which was concluded by IBGE on July 30<sup>th</sup>, 2018, ranges from -215 mm to -217 mm. In leveling segment 2 we obtained the normal height at starting point C by considering (Hofmann-Wellenhof and Moritz 2005, pp. 326):

$$(H^N - H^{NO}) = (N - \zeta) = \frac{\Delta g_B}{\gamma_m} * H^{NO} \quad (3)$$

Where  $H^{NO}$  and  $H^N$  are respectively the normal-orthometric and the normal heights in the local system,  $(N - \zeta)$  is the difference between the geoid height and height anomaly (see Fig. 2 and Fig. 3),  $\Delta g_B$  is the Bouguer anomaly (computed using GGM XGM2016 in this case) and  $\gamma_m$  is the mean normal gravity value between the telluroid and reference ellipsoid (see Fig. 2 and



Fig. 3). In either case (local or global system) normal height is related to the referred mean normal gravity value and the geopotential number according to this equation:

$$H_P^N = \frac{C_P}{\gamma_{m_P}} \quad (4)$$

If the normal height of the initial point  $H_i^N$  is known, then it is possible to obtain the normal heights (and geopotential numbers) along the leveling line if the normal height differences  $\delta H^N$  between neighboring points are known. Provisional values are obtained as follows:

$$H_{2_i}^N = H_{1_i}^N + \delta H_{(1-2)_i} \quad (5)$$

Where  $\delta H_{(1-2)_i}$  is the observed level difference. It is possible to obtain corrected values for normal height if corrected normal height differences  $\delta H_c^N$  are known using an iterative approach by applying the following equation, for example:

$$\delta H_{(1-2)_c}^N = \frac{g_{m_{(1-2)}} * \delta H_{(1-2)_i}}{\gamma_{m_2}} \quad (6)$$

Where the iteration is realized by recomputing the mean normal gravity value and the corrected normal height coming from the corrected normal height difference until there is stabilization in an iterative process, remembering that the mean normal gravity  $\gamma_m$  value between the ellipsoid and the telluroid can be computed by using a simple or a rigorous method.

By using a simple approximation, which is useful for many cases, such as in uneven regions, the simple method is:

$$\gamma_m = (2 * \gamma_{level\ ellipsoid} - 0,3086 * H_i^N) / 2 \quad (7)$$

Or by using a rigorous method such as the one used in this study (Gemael 1999):

$$\gamma_m = \gamma_{level\ ellipsoid} \left[ 1 - (1 + f + m - 2f \sin^2 \varphi) \frac{H_i^N}{a} + \frac{H_i^{N^2}}{a^2} \right] \quad (8)$$

Considering that  $f, m, a$  are constant parameters of the level ellipsoid associated with the GRS under consideration (see numerical values for GRS80 in Hofmann-Wellenhof and Moritz 2005, pp. 86).

The determination of  $\gamma_{level\ ellipsoid}$  can be done by applying the Clairaut theorem or the Somigliana formula. Both are functions of geodetic latitude and are based on geometric and physical parameters of the level ellipsoid (see, e.g. Hofmann-Wellenhof and Moritz 2005, pp. 71-72 and 86).

The corrected normal height  $H_c^N$  for each point in the segment is obtained after the convergence of the iterative process (usually two or three loops are sufficient).

$$H_{2_c}^N = H_{1_c}^N + \delta H_{(1-2)_c} \quad (9)$$

The determination of normal heights and geopotential numbers can be based on rigorous Normal Correction ( $NC$ ) to be applied on the observed level difference between two adjacent points in each leveled segment in substitution of Eq. 6 in the following form (Hofmann-Wellenhof and Moritz 2005, pp. 168):

$$NC_{(1-2)} = \sum_1^2 \frac{g-\gamma_0}{\gamma_0} \delta n + \frac{\gamma_{m1}-\gamma_0}{\gamma_0} H_1^N - \frac{\gamma_{m2}-\gamma_0}{\gamma_0} H_2^N \quad (10)$$

Its solution considers  $\gamma_0 = \gamma_{45^\circ} = 9.806199203 \text{ ms}^{-2}$  to be the normal gravity value for latitude  $45^\circ$ ,  $\gamma_m$  obtained by the previously mentioned iterative process and  $H_i^N$  of each point. Then  $H_c^N$  is obtained by considering e.g. between two points (1 and 2) the addition of  $NC_{(1-2)}$  to the observed level difference value  $\Delta n_{(1-2)}$ . This approach results in:

$$\Delta H_{(1-2)c}^N = H_{2c}^N - H_{1c}^N = \Delta n_{(1-2)} + NC_{(1-2)} \quad (11)$$

### 3.2 Proposed Solutions

**Solution 1:** This solution took into consideration gravity correction on the observed level differences in both leveling segments according to Eq. (6). Even considering that point A is not directly part of BVERF, it was considered that around point A the mean systematic difference previously referred to is observed:

$$H_{2018}^N - H_{2011}^{NO} \cong -216 \text{ mm} \quad (12)$$

It must be emphasized that the condition expressed in Eq. (12) was applied in all subsequent solutions.

**Solution 2:** Heights and geopotential numbers by considering the rigorous  $NC$  (Eq. 10) and initial conditions expressed in **Solution 1**.

**Observation:** It must be noted that GPS leveling involves open questions when applied to determine level differences with physical significance. The physical significance is obtained by considering the correction coming from the deflection of the vertical in a direct form on the GPS + gravimetry level differences or in an indirect form by using height anomaly differences derived from high-resolution GGMs, in a relative form, as explored below. This approach can be useful for improving the connection computation based on GPS leveling differences for obtaining normal height differences or geopotential number differences even in the local BVERF. This must be considered because the critical distances involved in the GPS + gravimetry leveling when comparing the usual sections of spirit leveling and the possibility of existing strong local physical effects coming from local crustal density anomalies.

**Solution 3:** Determination of normal heights in leveling segment 2 only based on GPS leveling associated with gravimetry and rigorous  $NC$ . In leveling segment 1 we take the same value for **Solution 2**. The aim of this approach was to test the GPS leveling procedure in heterogeneous conditions, involving level differences over heterogeneous distances ranging from 0.12km to 33km. This aspect must be explored in a future more rigorous investigation.

**Solution 4:** As per the observation made in **Solution 2** and because of the lack of external control over previous solutions based on GPS + gravimetry leveling, we introduced height resolution enhanced GGM as part of the solution. The basic selected functional was the differences of height anomaly in each GPS leveled section by high resolution enhanced GGM GECO 2015 with harmonic development up until degree and order 2190 (Gilardoni, Reguzzoni and Sampietro 2016). It must be stated that according to these authors this model involves an optimal least-squares combination between the EGM2008 (Pavlis et al. 2008) and GOCE spherical harmonic coefficients. Comparisons with other recent combined models, such as EIGEN-6C4 (Förste et al. 2014), and a local geoid/quasigeoid based on new gravity datasets show that the proposed combination, weighting the different input contributions not only on a global basis but also according to some local error information, can perform even better than other more sophisticated combinations in areas where the input global error description is not reliable enough. Solution 4 is more performant than the solution given by De Freitas et al. (2016) because the referred local error was not used in the enhancement of combined model in that solution as described in Ferreira, De Freitas and Heck (2015).

It is possible to observe in Fig. 4 (a, b, c and d) that in the region involved there are severe changes in the height anomaly. Note that all the considered models repeat similar behavior and patterns related to a strong variation of height anomaly in the region of leveling segment 1. It must be emphasized that the model satellite only based GOCO 05s (Mayer-Gürr 2015) is independent of some local reference frames and observations. Thus, the strong variation mentioned is real and reflects even on the satellite orbit of GOCE. This fact is not associated with observation errors. This anomaly evidently affects GPS + gravimetry leveling. We, therefore, introduced such variations as an indirect way for considering the discrepancies between the level ellipsoid and the geoid/quasigeoid.

**Solution 5:** Same as **Solution 4** but considering GGM XGM2016, with harmonic expansion up until degree and order 719. This model was adopted following suggestions by Nicacio, Dalazoana and De Freitas (2018) relating to the relative good behavior of this model in the region and the new approach used for its computation by considering its regional error behavior and data availability.

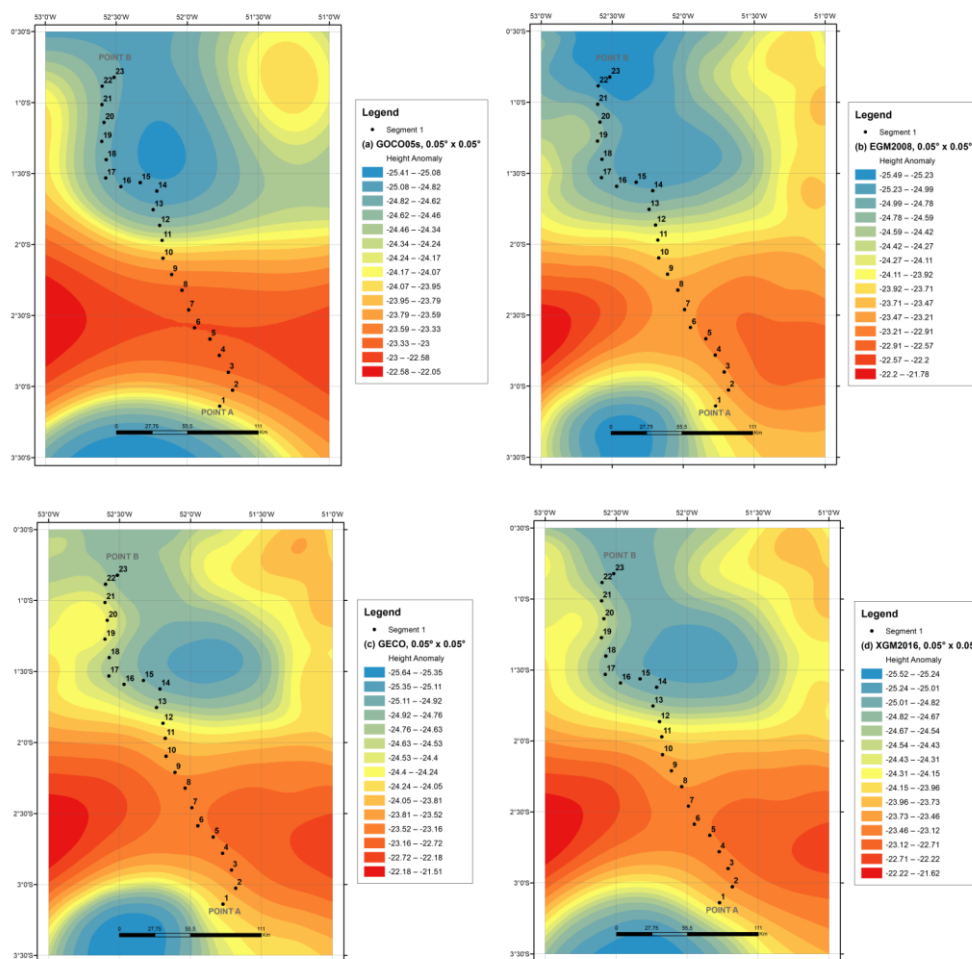
Each solution presented had the purpose of testing techniques for determining physical heights and geopotential numbers based on independent GBVP solution approaches. Table 4 presents the computed discrepancies for  $H_B^N$  and  $C_B$  for solutions coming from each leveling segment respectively linked to BVD – I (adopting different solutions at point A) and BVD – S (adopting point C as the origin).

**Table 4:** Normal Heights and Geopotential Numbers of point B using different solutions

Solution #	Normal Height (m)			Geopotential Number ( $m^2s^{-2}$ )		
	Segment 1	Segment 2	Discrepancy	Segment 1	Segment 2	Discrepancy
1	52.3402	51.8889	0.4512 *	511.9046	507.4915232	4.4131
2	52.3476	51.8936	0.4540*	511.9773	507.5371347	4.4401
3	52.3476	51.5543	0.7933*	511.9773	50,218282	7.7590
4	53.1311	51.8936	1.2374**	519.6400	507.5371347	12.1028
5	53.3131	51.8936	1.4195**	521.4203	507.5371347	13.8831

\*In these solutions, we can consider only error estimation of about  $\pm 0.11m$  at the initial point A related to the 2018 BVRF adjustment. Error propagation along segment 1 between points A and B as well as along segment 2 between points C and B cannot be controlled (open leveling lines). Each leveled point in segment 1 has an implicit error coming from the GPS ellipsoidal height determination of about  $\pm 0.05 m$ . There is no possibility of control in segment 2 between points B and C.

\*\* In these solutions there is the possibility of R.M.S estimation only based on the GGM used local determination of commission errors exists. Unfortunately, there are only estimates of such errors based on other GGMs.



**Figure 4:** Height anomaly maps derived from (a) Satellite only GGM GOCO 05s; (b) EGM2008 high resolution combined GGM; (c) Enhanced GECO GGM; (d) Next generation combined provisory XGM2016 GGM.

The five solutions explained are linked to level differences based on GPS ellipsoidal heights associated with gravimetry considering the BVRF 2018 realization. GPS leveling associated with gravimetry is the only current possibility in solving the physical connection in segment 1. We can note that among the solutions developed, **Solution 4** has more agreement with previous solutions summarized in section 2 (see Table 3). We emphasize that this solution is based on GPS observed level differences in segment 1 corrected by the difference of computed height anomalies from local observations and those modeled by GGM GECO.

Figure 5 shows the normal height discrepancy (between segment 1 related to BVD – I and segment 2, associated with BVD – S) at point B of all solutions performed in this research, which varies between 0.4512 m and 1.4195 m.

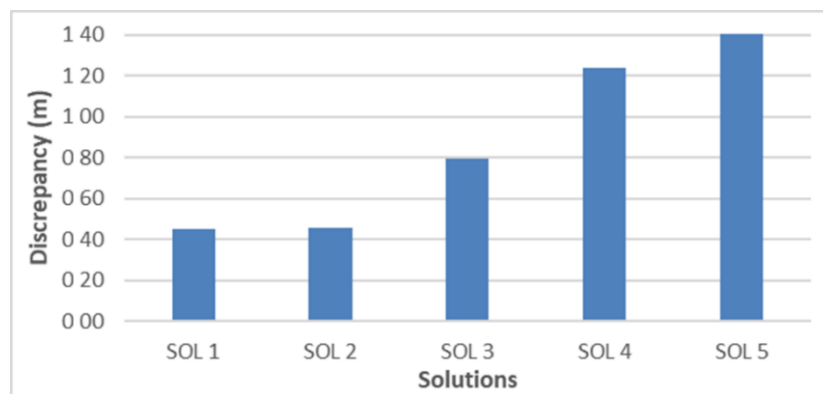


Figure 5: Normal height discrepancies at point B.

With the aim of checking the consistency of solutions based on GPS leveling and gravimetry, the recomputed height anomalies were considered in view of the corrections to the GPS level differences. Fig. 6 shows the height anomalies for Solution 2 (almost constant on the Fig. 6 scale) and Solutions 4 and 5 by considering the physical variations coming from regional existing crustal heterogeneities as shown in Fig. 4 by different GGMs.

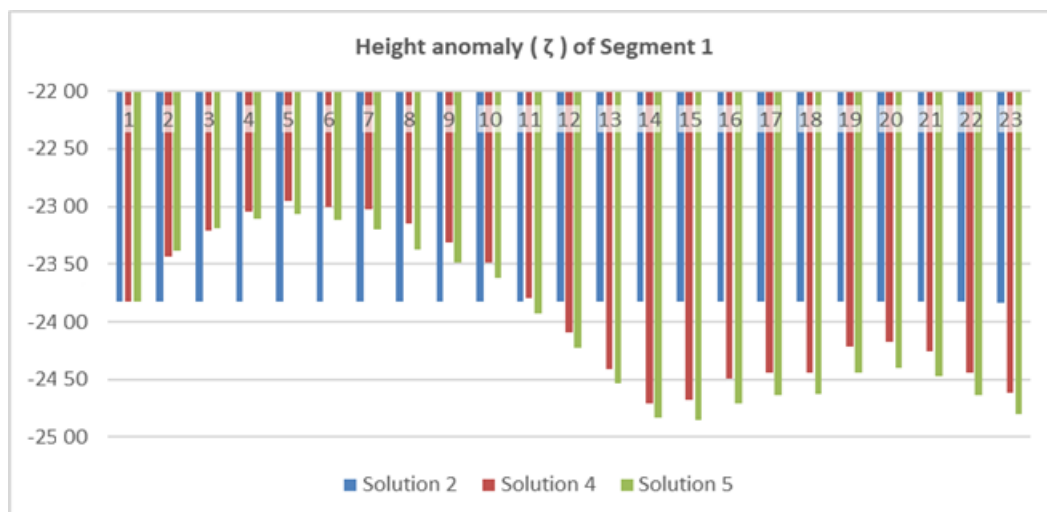


Figure 6: Height anomalies in Solutions 2, 4 and 5.

## 4. Remarks, Conclusions and Outlook

Five solutions for establishing the first leveling connection, with physical significance, point to point, between the two parts of BVERF were tested. Two leveling lines were made in the connection region (point A to point B, and point C to point B, as per Fig. 1). Segment A to B is about 270 km long and GPS associated with gravimetry was performed because of the land characteristics in the region. The other segment is about 170 km long and spirit leveling line associated with gravity was used. The solutions were compared with previous connection attempts based on indirect regional approaches in the geopotential space.

The previous indirect solutions in regional approaches have different characteristics to the new proposed point to point leveling solutions.

The previous solutions involved different realizations of BVERF, distributed GPS/Lev points with irregular distribution and little information on the BVD Santana side. An allowance was made for some error estimates based on a least square adjustment without, however, considering the possible error sources in the spirit leveling, GPS observations and commission and omission errors in the GGMs and DEMs used.

The five solutions proposed here depend strongly on point-based observations, mainly at points A, B, and C. It must be emphasized that GPS leveling aiming level differences with physical meaning is still an open subject of investigation. It was evidenced that solutions 1, 2 and 3, based on conventional gravity and normal corrections to level differences by GPS did not appear to address strong lateral heterogeneities in the Earth's gravity field along the leveling lines evidenced in Fig. 4.

Solutions 1 and 2 must be tested for short baseline among leveling stations. This is a fundamental step to be accomplished for understanding the viability of GNSS leveling associated only with local gravity corrections.

Solutions 4 and 5 integrate in a relative way the regional characteristics of crust based on two GGMs. Solution 4 is based on the high-resolution GECO enhanced model and Solution 5 is based on medium resolution GGM XGM2016, a previous test-model of the future EGM2020. Both enhanced models involve an optimum combination of harmonic coefficients of existing GGMs and the weighting of local errors for reducing local commission errors. This represents the cutting edge of development for generating a new generation of GGMs. Given the characteristics of the GECO model and comparisons with other recent models referred to, we consider Solution 4 to be the most controlled one.

It must be emphasized that Solution 4 shows good agreement with the previous solutions presented in Table 3. We emphasize the previous solution developed by De Freitas et al. (2016) in the determination of the offset between the two parts of BVERF, respectively 1.237 m (Solution 4, Table 4) and 1.200 m (Table 3). However, there is no clear possibility for quality control of these because they are based on open leveling lines.

A real possibility for establishing control on the connecting leveling lines is to determine geopotential numbers (or height anomalies) related to IHRF/IHRF and to check their discrepancies related to the height anomalies computed in the five solutions proposed. This approach assumes the resolution of the GBVP based on Molodensky gravity anomalies (also known as free-air surface

gravity anomalies) or based on surface gravity disturbances. A minimum control could be established by resolving GBVP at least at points A, B, and C.

## Acknowledgement

Author Andrea Santacruz thanks the National Secretary of Higher Education, Science, Technology, and Innovation (SENESCYT) - Ecuador for the scholarship received; author Silvio de Freitas thanks the Brazilian National Council for Scientific and Technological Development (CNPq - Grant process N. 306936/2015-1). The authors thank the following institutions for their fundamental support: Brazilian Geography and Statistics Institute (IBGE) for providing the data necessary for this research, and special mention to Dra. Sonia Costa Alves IBGE Geodesy Coordinator by the support, Federal University of Paraná (UFPR), Curitiba - Brazil and Prof. Vagner Ferreira of Hohai University (HU), Nanjing - China.

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**ERRATUM****Erratum of article:**

SANTACRUZ JARAMILLO, A.; FREITAS, S. R. and LUZ, R. T. 2019. Physical connection between BVRF segments based on leveling associated with gravimetry. *Boletim de Ciências Geodésicas*, v. 25, n.1, e2019006. doi 10.1590/s1982-21702019000100006

In the **page 1**, Authors:

**where it reads:**

Sílvio Rogério Correa de Freitas

**should read:**

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