

New conservation laws for inviscid Burgers equation

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Abstract. In this paper it is shown that the inviscid Burgers equation is nonlinearly self-adjoint. Then, from Ibragimov’s theorem on conservation laws, local conserved quantities are obtained.

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1 Introduction

In a previous work [4] the class of the self-adjoint equations (in the sense of the definition introduced by Ibragimov in [12]) of the type

$$u_t + f(t, x, u, u_x) = 0$$

was determined. In particular, it was proved that the inviscid Burgers equation

$$u_t + a(u)u_x = 0 \tag{1}$$

is (quasi) self-adjoint. In addition, from Ibragimov’s theorem on conservation laws [13], conservation laws for projectable Lie point symmetries (see [21]) of (1) were established.

Recently Maria Luz Gandarias [8] and Nail Ibragimov [17, 18, 19] have generalized the previous concepts of self-adjoint equations [12, 13, 14].

The recent developments allow one to find new conservation laws for equation (1). Thus in this paper the results obtained in [4] are complemented by using the new concepts [8, 17, 18, 19] combined with the powerful result [13].

The paper is organized as the follows: in the next section it is revisited Ibragimov's theorem on conservation laws and the concepts of self-adjoint equations. In the Section 3 the results regarding (1) obtained in [4] are discussed with the point of view of the new developments. In the following, some new conservation laws are established illustrating the results.

2 Revisiting previous results

2.1 Ibragimov's theorem on conservation laws

In what follows, it is assumed the summation over repeated indices, $x = (x^1, \dots, x^n)$ and $u = (u^1, \dots, u^m)$ denotes the independent variables and the dependent variables, respectively. The set of k th order derivatives and all differential functions of finite order shall be denoted by $\partial^k u$ and \mathcal{A} , respectively.

Ibragimov's theorem on conservation laws is

Theorem 2.1. *Any symmetry (Lie point, Lie-Bäcklund, nonlocal symmetry)*

$$X = \xi^i \frac{\partial}{\partial x^i} + \eta^\alpha \frac{\partial}{\partial u^\alpha} + \eta_i^\alpha \frac{\partial}{\partial u_i^\alpha} + \eta_{ij}^\alpha \frac{\partial}{\partial u_{ij}^\alpha} + \dots, \quad (2)$$

where $\xi^i, \eta^\alpha \in \mathcal{A}$, $\eta_i^\alpha = D_i(\eta^\alpha - \xi^j u_j^\alpha) + \xi^j u_{ij}^\alpha$, $\eta_{ij}^\alpha = D_i D_j(\eta^\alpha - \xi^k u_k^\alpha) + \xi^k u_{kij}^\alpha$, etc, of the system of equations

$$F_\alpha(x, u, \partial u, \dots, \partial^s u) = 0 \quad (3)$$

with n independent variables $x = (x^1, \dots, x^n)$ and m dependent variables $u = (u^1, \dots, u^m)$ is inherited by the adjoint equation. Specifically the operator

$$Y = \xi^i \frac{\partial}{\partial x^i} + \eta^\alpha \frac{\partial}{\partial u^\alpha} + \eta_*^\beta \frac{\partial}{\partial v^\beta} \quad (4)$$

with an appropriately chosen coefficient η_* is admitted by the system of equations (3) and its adjoint system

$$F_\alpha^*(x, u, v, \partial u, \partial v, \dots, \partial^s u, \partial^s v) := \frac{\delta(v^\beta F_\beta)}{\delta u^\alpha} = 0. \quad (5)$$

Furthermore, the combined system (3) and (5) has the conservation law $D_i C^i = 0$, where

$$\begin{aligned}
 C^i = & \xi^i \mathcal{L} + W_\alpha \left[\frac{\partial \mathcal{L}}{\partial u_i^\alpha} - D_j \left(\frac{\partial \mathcal{L}}{\partial u_{ij}^\alpha} \right) + D_j D_k \frac{\partial \mathcal{L}}{\partial u_{ijk}^\alpha} - \dots \right] \\
 & + D_j (W^\alpha) \left[\frac{\partial \mathcal{L}}{\partial u_{ij}^\alpha} - D_k \left(\frac{\partial \mathcal{L}}{\partial u_{ijk}^\alpha} \right) + \dots \right] \\
 & + D_j D_k (W^\alpha) \left[\frac{\partial \mathcal{L}}{\partial u_{ijk}^\alpha} - \dots \right] + \dots
 \end{aligned} \tag{6}$$

and $W^\alpha = \eta^\alpha - \xi^i u_i^\alpha$.

2.2 Quasi-self-adjoint and self-adjoint equations

The following definitions were introduced in [12, 13, 14].

Definition 2.2. An equation $F = 0$ is said to be self-adjoint if there exists a function $\phi = \phi(x, u, \dots)$ such that $F^*|_{v=u} = \phi F$. Thus $F^*|_{v=u} = 0$ if and only if $F = 0$.

Definition 2.3. An equation $F = 0$ is said to be quasi-self-adjoint if there exists a function $\phi = \phi(x, u, \dots)$ such that $F^*|_{v=\varphi(u)} = \phi F$, with $\varphi'(u) \neq 0$. Thus $F^*|_{v=\varphi(u)} = 0$ if and only if $F = 0$.

Whenever an equation is quasi-self-adjoint or self-adjoint, formulae (6) allow one to construct local conservation laws for the considered equation insteading of v by $\varphi(u)$ or u , respectively.

Recently many authors have been employing these concepts in order to establish conservation laws for equations and systems. For instance, Ibragimov, Torrisi and Tracinà determined the class of quasi-self-adjoint system derived from a $(2 + 1)$ generalized Burgers equation in [16]. Bruzón, Gandarias and Ibragimov determined a class of self-adjoint differential equations in [3]. Conservation laws for the Camassa-Holm equation was obtained by Ibragimov, Khamitova and Valenti in [20]. Further examples can be found in [4, 5, 15].

2.3 Conservation laws for inviscid Burgers equation

The adjoint equation to (1) is (see [4])

$$v_t + a(u)v_x = 0. \quad (7)$$

Let $F = v_t + a(u)u_x$. Then it is easy to see that $F^*|_{v=\varphi(u)} = -\varphi'(u)(u_t + a(u)u_x)$. Thus (1) is quasi-self-adjoint, for all smooth function $\varphi = \varphi(u)$. In particular, this holds for $\varphi = u$ and equation (1) is also self-adjoint.

From Ibragimov's theorem on conservation laws, a conserved vector for equation (1) is

$$\begin{aligned} C^0 &= [\eta + (\tau a(u) - \xi) u_x] \varphi(u), \\ C^1 &= [\eta a(u) - (\tau a(u) - \xi) u_t] \varphi(u), \end{aligned} \quad (8)$$

where

$$X = \tau(x, t, u) \frac{\partial}{\partial t} + \xi(x, t, u) \frac{\partial}{\partial x} + \eta(x, t, u) \frac{\partial}{\partial u}$$

is a Lie point symmetry generator of (1).

3 New conservation laws for equation (1)

Definitions 1 and 2 have been extended to

Definition 3.1. An equation $F = 0$ is said to be nonlinearly self-adjoint if the equation obtained from the adjoint equation (5) by the substitution $v = \varphi(x, u)$ with a certain function $\varphi(x, u) \neq 0$ is identical with the original equation (3), that is,

$$F^*|_{v=\varphi(x,u)} = \phi(x, u, \dots)F, \quad (9)$$

for some $\phi \in \mathcal{A}$.

Whenever (9) holds for a certain function φ such that $\varphi_u \neq 0$ and $\varphi_{x^i} \neq 0$, the equation $F = 0$ is called weak self-adjoint.

Remark 3.1. The concept of nonlinearly self-adjoint equations was introduced by Ibragimov, see [17, 18, 19]. On the other hand, the notion of weak self-adjoint equation was introduced by Gandarias in [8].

With respect to these new concepts, weak self-adjointness for evolution equations were obtained in [9, 10, 11]. Namely, in [10] Gandarias, Redondo and Bruzón applied the new concept to a class of equations arising in financial mathematics. In [9] Gandarias established local conservation laws for a porous medium equation using the self-adjointness of the equation under consideration. More recently Gandarias and Bruzón [11] found a class of weak self-adjoint forced KdV equations.

Nonlinearly self-adjointness have been focused by Freire and Sampaio in [6], where the authors determined a class of nonlinear self-adjoint equations of fifth-order. In [2] Bozhkov, Freire and Ibragimov showed that the nonlinear self-adjointness of the Novikov equation (further details, see [2] and references therein) implies in the strictly self-adjointness of that equation. In [7] new classes of self-adjoint equations up to fifth-order were found.

Taking the nonlinearly self-adjointness for differential equations into account, substituting $v = \psi(x, t, u)$ into (7) and using (1), it is obtained

$$\psi_t + a(u)\psi_x = 0. \quad (10)$$

A solution to (10) is $\psi(x, t, u) = \phi(z) + \varphi(u)$, with $z = x - ta(u)$.

From Ibragimov's theorem on conservation laws, a local conservation law for equation (1) is given by

$$\begin{aligned} C^0 &= [\eta + (\tau a(u) - \xi) u_x] (\phi(z) + \varphi(u)), \\ C^1 &= [\eta - (\tau a(u) - \xi) u_t] (\phi(z) + \varphi(u)), \end{aligned} \quad (11)$$

where $z = x - ta(u)$.

In fact, the new conserved vector obtained from the self-adjointness' new concept is $C = (C^0, C^1)$, where

$$\begin{aligned} C^0 &= [\eta + (\tau a(u) - \xi) u_x] \phi(x - ta(u)), \\ C^1 &= [\eta a(u) - (\tau a(u) - \xi) u_t] \phi(x - ta(u)). \end{aligned} \quad (12)$$

Observe that (12) possibilites to find an infinite number of new conservation laws for a fixed Lie point symmetry generator of equation (1).

4 Examples

Here it will be established some conservation laws illustrating the results obtained previously. Consider the Lie point symmetry generator

$$X_4 = t \frac{\partial}{\partial t} - \frac{a(u)}{a'(u)} \frac{\partial}{\partial u} \quad (13)$$

of equation (1). Here it is used the same notation employed in [4]. Substituting the components of (13) into (12) it is obtained

$$\begin{aligned} C^0 &= \left[-\frac{a(u)}{a'(u)} + ta(u) u_x \right] \phi(x - ta(u)), \\ C^1 &= \left[-\frac{a(u)^2}{a'(u)} - ta(u) u_t \right] \phi(x - ta(u)). \end{aligned} \quad (14)$$

Setting $\phi(z) = z$ into (14), it is found that the conserved vector is $C = (C^0, C^1)$, where

$$\begin{aligned} C^0 &= -\frac{a(u)}{a'(u)}(x - ta(u)) - tA(u) + D_x (txA(u) - t^2\alpha(u)), \\ C^1 &= -\frac{a(u)^2}{a'(u)}(x - ta(u)) + xA(u) - 2t\alpha(u) + D_t (t^2\alpha(u) - txA(u)) \end{aligned}$$

α is given by $A'(u) = a(u)$ and β is a function such that $\alpha'(u) = a(u)^2$. Transferring the terms $D_x(\dots)$ from C^0 to C^1 and simplifying, it is obtained the conserved vector $C = (C^0, C^1)$, with components given by

$$\begin{aligned} C^0 &= -\frac{a(u)}{a'(u)}(x - ta(u)) - tA(u), \\ C^1 &= -\frac{a(u)^2}{a'(u)}(x - ta(u)) + xA(u) - 2t\alpha(u). \end{aligned}$$

Recently new Lie point symmetries of the inviscid Burgers equations were found, see [1]. In the next example we use the new generator (it is employed the same notation of the original paper [1])

$$Z_{11} = (x - ta(u)) \frac{\partial}{\partial x}$$

for establishing another conservation laws for (1). Let $\phi = c_1(x - ta(u)) + c_2$, $\varphi = c_3u^p + c_4/u$, $p \neq -1$, where $c_1, c_2, c_3, c_4 \in \mathbb{R}$ are arbitrary constants,

$A'(u) = a(u)$, $B'(u) = a(u)u^p$, $U' = a(u)/u$ and $\alpha' = a(u)^2$. From (10) it is obtained

$$\begin{aligned} C^0 &= -c_1(x - ta(u))^2u_x - c_2(x - ta(u))u_x \\ &\quad - c_3(x - ta(u))u_x - c_4\frac{x - ta(u)}{u}u_x, \\ C^1 &= c_1(x - ta(u))^2u_t + c_2(x - ta(u))u_t \\ &\quad + c_3(x - ta(u))u_t + c_4\frac{x - ta(u)}{u}u_t. \end{aligned}$$

Since

$$\begin{aligned} C^0 &= c_1[D_x(2xtA - x^2u - t^2\alpha) + 2xu - 2tA] + c_2[D_x(tA - xu) + u] \\ &\quad + c_3\left[D_x\left(tB - x\frac{u^{p+1}}{p+1}\right) + \frac{u^{p+1}}{p+1}\right] + c_4\left[D_x\left(x \ln |u| + \frac{ta(u)}{u}\right) + \ln |u|\right], \\ C^1 &= c_1[D_t(x^2u + t^2\alpha - 2xtA) + 2xA - 2t\alpha] + c_2[D_t(xu - tA) + A] \\ &\quad + c_3\left[D_t\left(x\frac{u^{p+1}}{p+1} - tB\right) + B\right] + c_4[D_t(x \ln |u| - tU) + U], \end{aligned}$$

by transferring the terms $D_t(\dots)$ from C^1 to C^0 , it is obtained

$$\begin{aligned} C^0 &= c_1(2xu - 2tA) + c_2u + c_3\frac{u^{p+1}}{p+1} + c_4 \ln |u|, \\ C^1 &= c_1(2xA - 2t\alpha) + c_2A + c_3B + c_4U. \end{aligned}$$

It is easy to see that the conserved vector obtained is a linear combination of the conserved vectors

$$\begin{aligned} D_1 &= (2xu - 2tA, 2xA - 2t\alpha), \quad D_2 = (u, A), \\ D_3 &= \left(\frac{u^{p+1}}{p+1}, B\right), \quad D_4 = (\ln |u|, U). \end{aligned}$$

5 Conclusion

In this paper the previous results on conservation laws obtained by the author in [4] are generalized using the recent new developments due to Maria L. Gandarias [8] and Nail H. Ibragimov [17, 19]. The main result is the new conserved vector (12). In particular, the results obtained here possibilite one to construct an infinite number of new conservation laws for equation (1).

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