

A Note on the Complexity of Scheduling Coupled Tasks on a Single Processor*

Jacek Błażewicz¹, Klaus Ecker², Tamás Kis³, Michał Tanaś¹

¹ Institute of Computing Science, Poznań University of Technology, Poznań, Poland

² Institute of Computing Science, Technical University Clausthal, Germany

³ University of Siegen, Germany

Abstract

This paper considers a problem of coupled task scheduling on one processor, where all processing times are equal to 1, the gap has exact length h , precedence constraints are strict and the criterion is to minimise the schedule length. This problem is introduced e.g. in systems controlling radar operations. We show that the general problem is NP-hard.

Keywords: Scheduling, coupled tasks, NP-hardness.

1 Introduction

A scheduling problem is, in general, a problem answering a question of how to allocate some resources over time in order to perform a given set of tasks [1]. In practical applications resources are processors, money, manpower, tools, etc. Tasks can be described by a wide range of parameters, like ready times, due dates, relative urgency factors, precedence constraints and many more. Different criteria can be applied to measure the quality of a schedule. The general formulation of scheduling problems and the commonly used notation can be found in books such as [5], [16], [2], [15], [3] and [4]. A survey of the most important results is given in [11].

One branch of scheduling theory is concerned with scheduling of coupled tasks. A task is called *coupled* if it contains two operations where the second has to be processed some time after a completion of the first one. This problem, described in [17] and [18], often appears in radar-like devices, where the first operation is the transmission of an electromagnetic pulse and the second is the reception of its echo. Several algorithms designed to solve the problem of radar pulse scheduling can be found in [9] and [12].

The complexity of various scheduling problems with coupled tasks has been studied in [13]. Although most of the cases are NP-hard [13], some polynomial algorithms were found in [14].

A coupled task scheduling problem with variable length gap is surveyed in [10] and [7]. NP-hardness of this case is proved in [19], where some interesting connections between coupled tasks and flow shops are also given.

In this note, we complement the above results by presenting the NP-completeness proof for the problem of scheduling coupled tasks on a single processor, with all processing times equal to 1, exact, integer gap length, general strict precedence constraints and the optimisation criteria of minimising the schedule length.

An organisation of the paper is as follows. The problem is formulated in Section 2. The NP-hardness proof is presented in Section 3. We conclude in Section 4.

2 Problem formulation

We consider the problem of scheduling n coupled tasks on a single machine, where each coupled task T_i consists of two operations T_{i1} and T_{i2} and a *gap* between them. During the gap, another task can be processed. Let p_{i1} and p_{i2} denote the processing times of operations T_{i1} and T_{i2} , respectively.

The gap is exact when operation T_{i2} has to start exactly h_i units of time after the end of operation T_{i1} , where h_i denotes a length of the gap. In this paper, the only cases considered are those where all h_i are equal, i.e. $h_i = h, i = 1, 2, \dots, n$.

Precedence constraints of coupled tasks can be strict or weak. $T_i \prec T_j$ means that $T_{i2} \prec T_{j1}$ if precedence constraints are *strict*, and $T_{i1} \prec T_{j1} \wedge T_{i2} \prec T_{j2}$ if they are *weak*.

The special case of a coupled task problem involves identical tasks. Commonly, such tasks are

*Partially supported by the KBN grant.

denoted by (p_1, h, p_2) , where $p_1 = p_{i1}$, $p_2 = p_{i2}$, $h = h_i$ for all $1 \leq i \leq n$.

Adapting the commonly accepted notation for scheduling problems [8], the scheduling problem considered in this paper can be denoted by $1|(1, h, 1) - \text{coupled, strict prec, exact gap}|C_{max}$, which means:

- There is one processor in a system.
- Tasks are coupled and identical, with processing times $p_{i1} = p_{i2} = 1$, $\forall 1 \leq i \leq n$
- Gaps are exact and have uniform length h .
- Precedence constraints are strict.
- The optimisation criterion is to minimise the schedule length $C_{max} = \max\{t_{j2}\}$, where t_{j2} is a completion time of T_j (its second operation).

3 NP-hardness of the general case

In case where precedence constraints are general the problem of scheduling coupled tasks on a single processor is NP-hard even for unit processing times. We will prove this by a series of lemmata showing NP-hardness of some intermediate problems.

Lemma 1 Problem of *Balanced Colouring of Graphs with Partially Ordered Vertices* is NP-hard.

Proof: The problem of *Balanced Colouring of Graphs with Partially Ordered Vertices* (BCGPOV for short) can be stated as follows:

Instance: A directed, acyclic graph $G = (V, E)$ where $|V| = q$. (It is clear that the arcs define a partial order in set V .)

Question: Can the vertices of G be coloured with l colours such that no pair of adjacent vertices shares the same colour and exactly q/l vertices are coloured with the same colour. (We will call such a colouring the *balanced colouring*.) Without loss of generality we can assume that $q/l \in \mathbb{Z}^+$.

Firstly, we prove that BCGPOV belongs to *class NP*. To verify a solution of BCGPOV is enough to verify that

No pair of adjacent vertices is monochromatic. Because each vertex has no more than $(q-1)$ adjacent vertices the complexity of this step is $O(q^2)$.

Exactly q/l vertices are coloured with each colour. Complexity of this step is $O(q)$.

A solution of BCGPOV can be verified in polynomial time, which means that the problem BCGPOV belongs to *class NP*.

In order to prove NP-completeness of the problem BCGPOV we will use the *3-Partition* problem, which is NP-complete in the strong sense according to [6]. The *3-Partition* problem is defined as follows:
Instance: A collection A of $3r$ items, bound $B \in \mathbb{Z}^+$, and size $s(a_j) \in \mathbb{Z}^+$, $\forall a_j \in A$ such that $B/4 < s(a_j) < B/2$ and such that $\sum_{a_j \in A} s(a_j) = rB$.

Question: Can A be partitioned into r disjoint sets A_1, \dots, A_r such that for $1 \leq i \leq r$, $\sum_{a_j \in A_i} s(a_j) = B$ (note that each A_i must contain exactly three elements from A)?

The transformation: For any instance of the *3-Partition* problem let us define the corresponding instance of the BCGPOV problem as follows:

- $q = 3r^2 + rB$
- $l = r$
- For each item $a_j \in A$, $1 \leq j \leq 3r$ let us construct graph G_j in the following way:

1. Construct complete graph K_r^j on r vertices. Denote one vertex of K_r^j by v_j .
2. Construct set $D_{s(a_j)}^j$ of $s(a_j)$ independent vertices.
3. Create all possible edges (v_x, v_y) such that $v_x \in K_r^j$, $v_x \neq v_j$ and $v_y \in D_{s(a_j)}^j$.

It is clear that edges of graph G_j can be directed to define a partial order in the set of vertices of G_j .

An example of such a graph is shown in Fig 1.

- $G = \bigcup_{i=1}^{3r} G_j$

It is clear that G_j can be coloured with r colours only in the following way: each vertex from K_r^j has a different colour and all vertices from $D_{s(a_j)}^j$ are coloured with the same colour as vertex v_j .

No two vertices of any subgraph K_r^j , $1 \leq j \leq 3r$ can share the same colour, so after colouring of all K_r^j , exactly $3r$ vertices are coloured with the same colour. All vertices of $D_{s(a_j)}^j$ are connected with all but v_j vertices of K_r^j , so all vertices of $D_{s(a_j)}^j$ have to be coloured with the same colour as vertex v_j . So, the set of vertices of any $D_{s(a_j)}^j$ has to be monochromatic.

Let A_1, \dots, A_j be a solution for the given instance of *3-Partition* problem and let $A_i = \{a_{i(1)}, a_{i(2)}, a_{i(3)}\}$. Let us denote $S_i = G_{i(1)} \cup G_{i(2)} \cup G_{i(3)}$. G can be coloured such

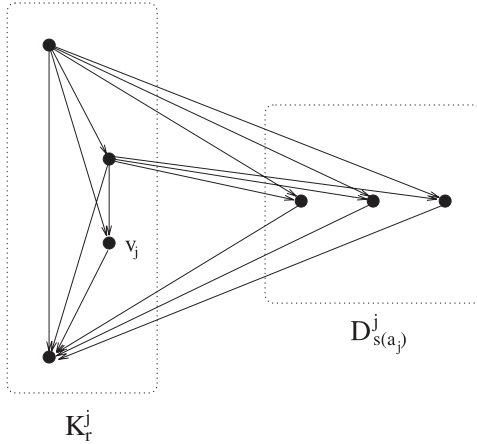


Figure 1: An example of graph G_j , where $q = 4$, $s(a_j) = 3$.

that sets D_i and D_j share the same colour if and only if both D_i and D_j are in the same S_i . It means that for all i exactly $s(a_{i(1)}) + s(a_{i(2)}) + s(a_{i(3)}) = B$ vertices of sets D , so exactly $3r + B$ vertices of graph G , are coloured with each colour.

On the other hand, let S_1, S_2, \dots, S_r be a disjoint sets of vertices of graph G , such that $V(G) = \sum_{i=1}^r S_i$, each vertex in S_i is coloured with i -th colour and $\forall_i |S_i| = 3r + B$. Let S_i^D be a subset of S_i that contains only vertices belonging to $D_{s(a_j)}^j$ subgraphs. S_i has to contain $3r$ vertices belonging to K_r^j , so $|S_i^D| = B$ for each i . For each feasible colouring each $D_{s(a_j)}^j$ is monochromatic, so $\forall_{1 \leq j \leq 3r} \exists_{1 \leq i \leq r} D_{s(a_j)}^j \in S_i$. Because $\forall_{1 \leq j \leq 3r} B/4 < s(a_j) < B/2$ each S_i has to contain exactly 3 subgraphs $D_{s(a_{i(j)})}^{i(j)}$, $j = 1, 2, 3$. So, we can denote $A_i = \{a_{i(j)} : j = 1, 2, 3\}$, $i = 1, 2, \dots, r$ and this is the solution of the 3 -Partition problem.

The complexity of this transformation is $O(r^2 + rB)$. Let us note that this is a pseudopolynomial transformation. On the other hand, 3 -Partition is NP-complete, thus, we have the desired result.

□

Now, we will show that problem $BCGPOV$ polynomially transforms to our scheduling problem.

Lemma 2 The problem of *Balanced Colouring of Graphs with Partially Ordered Vertices* polynomially transforms to $1|(1, h, 1) - \text{coupled, strict prec, exact gap}|C_{max}$.

Proof: Let $G = (V, E)$ be an instance of problem $BCGPOV$. Let it contain all transitive arcs. Let us define a corresponding instance of $1|(1, h, 1) - \text{coupled, strict prec, exact gap}|C_{max}$ problem in the following way:

- $n = q$
- $h = q/l - 1$
- For each vertex v_i of graph G define the coupled task T_i .
- For each arc (v_i, v_j) of graph G define an arc $T_i \prec T_j$ of precedence constraints in the scheduling problem.
- $y = C_{max} = 2n$.

Let us assume that a balanced colouring of G exists. Let S_1, S_2, \dots, S_l be subsets of $V(G)$ such that $\bigcup_{i=1}^l S_i = V(G)$, and all vertices that belong to S_i are coloured with the i -th colour and $\forall_{1 \leq i \leq l} |S_i| = q/l$. Sets S_i are partially ordered because vertices of G are partially ordered and G contains all transitive arcs. Schedule sets S_i in accordance to the partial order using the following algorithm:

Algorithm 1

```

begin
  s := 0
  repeat
    Get a task  $T_j \in S_i$ .
    Let  $s$  be the starting time of the task  $T_j$ .
     $S_i := S_i \setminus T_j$ 
     $s := s + 1$ 
  until  $S_i \neq \emptyset$ 
end;
```

The schedule generated in such way is shown in Fig. 2.



Figure 2: Schedule of set $S_i = \{T_a, T_b, T_c, T_d, T_e\}$ where $h = 4$.

This procedure guarantees that no precedence constraint will be violated. The schedule contains no idle intervals, so its length is y .

On the other hand, let us assume that a schedule of length y for the given instance of the coupled tasks problem exists. The schedule does not contain idle intervals, so it has to be a sequence of segments as shown in Fig. 2. Each segment contains

$h+1$ independent tasks, which means that the corresponding vertices in G are also independent. So, the vertices from one segment can be coloured with the same colour, which means G can be coloured with $n/(h+1)$ colours such that exactly $h+1$ vertices shares the same colour.

□

Now we can conclude.

Theorem 1 Problem $1|(1, h, 1) -$
coupled, strict prec, exact gap | C_{max} is NP-hard.

Proof: Follows immediately Lemmae 1 and 2.

□

4 Conclusions

In the paper, scheduling of coupled tasks has been considered. General precedence constraints resulted in a strong NP-hardness of the problem, even for unit processing times and equal gap lengths for all the tasks. The other cases, especially where precedence constraints are chain-like or tree-shaped are still open.

References

- [1] K. Baker, *Introduction to Sequencing and Scheduling*, J. Wiley, New York, 1974
- [2] J. Blażewicz, W. Cellary, R. Słowiński and J. Węglarz, *Scheduling under Resource Constraints: Deterministic Models*, J. C. Baltzer, Basel, 1986.
- [3] J. Blażewicz, K. H. Ecker, E. Pesch, G. Schmidt and J. Węglarz, *Scheduling Computer and Manufacturing Processes* (2nd edition), Springer, Berlin, New York, 2001.
- [4] J. Blażewicz, K. H. Ecker, B. Plateu, D. Trystam, *Handbook of Parallel and Distributed Processing*, Springer, Berlin, New York, 2000.
- [5] R. W. Conway, W. L. Maxwell and L. W. Miller, *Theory of Scheduling*, Addison-Wesley, Reading, Mass. 1967.
- [6] M. R. Garey, D. S. Johnson, *Computers and Intractability: A Guide to the Theory of NP-Completeness*, W.H. Freeman, San Francisco, 1979.

- [7] J. N. D. Gupta *Single facility scheduling with two operations per job and time-lags*, preprint, 1994.
- [8] L. R. Graham, E. L. Lawler, J. K. Lenstra, A. H. G. Rinnooy Kan, Optimization and approximation in deterministic sequencing and scheduling theory: a survey, *Ann. Discrete Math.* **5**, 1979, 287-326.
- [9] A. Farina, P. Neri, Multitarget interleaved tracking for phased radar array, *IEEE Proceedings F* **27**, 1980, 312-318.
- [10] W. Kern, W. M. Nawijn, *Scheduling multi-operations jobs with time lags on a single machine*, preprint, 1991.
- [11] E. L. Lawler, J. K. Lenstra, A. H. G. Rinnooy Kan, D. B. Shmoys, Sequencing and scheduling: algorithms and complexity, in S. C. Graves et al, *Handbooks in Operations Research and Management Science* **4**, North-Holland, Amsterdam, 1993
- [12] D. J. Milojevic, B. M. Popovic, Improved algorithm for the interleaving of radar pulses, *IEEE Proceedings F* **139**, 1992, 98-104..
- [13] A. J. Orman, C. N. Potts, On the complexity of coupled tasks scheduling, *Discrete Applied Mathematics* **72**, 1997, 141-154.
- [14] A. J. Orman, C. N. Potts, A. K. Shahani, A. R. Moore, Scheduling for the control of a multifunctional radar system, *European Journal of Operational Research* **90**, 1996, 13-25.
- [15] M. Pinedo, *Scheduling: Theory, Algorithms and Systems*, Prentice Hall, Englewood Cliffs, N. J., 1995.
- [16] A. H. G. Rinnooy Kan, *Machine Scheduling Problems: Classification, Complexity and Computations*, Martinus Nijhoff, The Hague, 1976.
- [17] R. D. Shapiro, Scheduling coupled tasks, *Naval. Res. Logist. Quart.* **27**, 1980, 477-481.
- [18] A. J. Orman, A. K. Shahani and A. R. Moore, Modelling for the control of a complex radar system, *Computers Ops Res.* **25**, 1998, 239-249.
- [19] W. Yu, *The Two-machine Flow Shop Problem with Delays and the One-machine Total Tardiness Problem*, Ph. D. Thesis, Technische Universiteit Eindhoven, 1996.