

Division - Soil in Space and Time | Commission - Pedometry

Spatial Disaggregation of Multi-Component Soil Map Units Using Legacy Data and a Tree-Based Algorithm in Southern Brazil

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ABSTRACT: Soil surveys often contain multi-component map units comprising two or more soil classes, whose spatial distribution within the map unit is not represented. Digital Soil Mapping tools supported by information from soil surveys make it possible to predict where these classes are located. The aim of this study was to develop a methodology to increase the detail of conventional soil maps by means of spatial disaggregation of multi-component map units and to predict the spatial location of the derived soil classes. Three digital maps of terrain variables - slope, landforms, and topographic wetness index - were correlated with the soil map and 72 georeferenced profiles from the Porto Alegre soil survey. Explicit rules that expressed regional soil-landscape relationships were formulated based on the resulting combinations. These rules were used to select typical areas of occurrence of each soil class and to train a decision tree model to predict the occurrence of individualized soil classes. Validation of the soil map predictions was conducted by comparison with available soil profiles. The soil map produced showed high agreement (80.5 % accuracy) with the soil classes observed in the soil profiles; Ultisols and Lithic Udorthents were predicted with greater accuracy. The soil variables selected in this study were suitable to represent the soil-landscape relationships, suggesting potential use in future studies. This approach developed a more detailed soil map relevant to current demands for soil information and has potential to be replicated in other areas in which data availability is similar.

Keywords: digital soil mapping, soil-landscape relationships, decision trees.

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INTRODUCTION

The important role of soils in maintaining life on Earth dictates they should be used in a sustainable way and highlights the need for pedological information, such as soil properties and spatial distribution. The most common source of this information is the soil survey, which generally comprises a soil map accompanied by a descriptive report with a dataset of independent pedons.

However, Brazilian soil surveys that cover the entire country only exist at the reconnaissance level, containing soil maps with small scales (less than 1:750,000), and more detailed maps are rarely available (Giasson et al., 2006). Because of the small scale of these maps and/or complex arrangement of soils in the landscape, in most cases a map unit (MU) aggregates more than one soil component, forming a multi-component MU. Thus, there is no graphical representation of the distribution of these components in the soil map in these multi-component MU, and the only information contained in the survey report describes their general spatial distribution in the landscape and/or the percentage of each component within the MU. With these characteristics, they may not meet current demands for soil information, e.g., the valuation of ecosystem services provided by soils or the delineation of wetlands (Vincent et al., 2018).

However, existing soil surveys can be an important starting point for generating more detailed soil maps. One possibility to refine information on soil distribution is to use spatial disaggregation of multi-component MUs. Spatial disaggregation follows Digital Soil Mapping (DSM) techniques and environmental covariates to separate soil components within a multi-component MU, based on spatial relationships or patterns between soils and the landscape (Sarmiento et al., 2017; Vincent et al., 2018). The objective is to use a map with fewer details to produce an enhanced map that represents the distribution of the soil components, i.e., a map with more single MUs (Nauman et al., 2014). Spatial disaggregation of the multi-component MUs takes advantage of valuable sources of information, such as legacy data, which can be observational points (independent pedons) and/or soil maps with their respective descriptive reports.

Tree-based models have been widely used in soil class prediction with DSM, due to ease of understanding and discussion, the ability to process large datasets, and robustness as a predictive technique (ten Caten et al., 2012; Bagatini et al., 2016). Following the same logic of conventional soil mapping, in which pedologists seek to establish conceptual relationships between soils and environmental parameters, DSM tree-based models can be used to correlate soil components or properties with environmental covariates, e.g., elevation and slope, to produce more detailed maps. These algorithms have been used for the disaggregation of multi-component MUs of conventional soil maps (Håring et al., 2012; Nauman et al., 2014; Nauman and Thompson, 2014; Sarmiento et al., 2017; Vincent et al., 2018) or geological studies (Bui and Moran, 2001) and to describe the spatial variation of soil properties, such as organic carbon, with more detail (Kerry et al., 2012).

We aimed to present a methodology to increase the detail of a soil map by disaggregating the multi-component MUs of the soil map of the municipality of Porto Alegre using available soil information and tree models to generate an enhanced soil map. This approach based on available legacy data allows substantial reduction in the number and extent of field trips, which are a considerable part of the cost of a soil survey.

MATERIALS AND METHODS

Study area

The study area is the municipality of Porto Alegre, Rio Grande do Sul, Brazil, which covers approximately 49,668 ha (Figure 1). Most of the parent material in the area is composed of granitic rocks and granodioritic to dioritic gneisses, forming crests and

hills. At lower levels, there are more recent formations, such as eluvial deposits of granites and gneisses and partially reworked colluvial and alluvial deposits, the latter forming terraces and sand barriers. Along the streams and on the islands in the Jacuí River delta, deposits of sediments of fluvial origin occur. On the banks of Guaíba Lake, more recent lagoon and marine sediment deposits form sand coastal plains (Philipp, 2008). The elevation ranges from 0.1 m (Jacuí River delta) to 311 m (Santana Hill) (Penter et al., 2008; Hasenack et al., 2010).

The region is in a transition between two major Brazilian biomes, the Pampas and the Atlantic Forest; the vegetation comprises a mosaic of wood- and grasslands, as well as various pioneer formations (Hasenack et al., 2008). The climate, according to Köppen system, is Subtropical Humid (*Cfa*), with an annual mean temperature of 19.5 °C and annual mean rainfall of 1,320 mm, well distributed throughout the year (Inmet, 2016).

The most common soils classes according to Soil Taxonomy (Soil Survey Staff, 2014) and Brazilian Soil Classification System (Santos et al., 2013) are Ultisols (*Argissolo Vermelho Distrófico*), Inceptisols (*Cambissolo Háplico Alítico*), and Lithic Udorthents (*Neossolo Litólico Distrófico*), usually found at higher elevations, whereas Albaquults (*Planossolo Háplico Distrófico*), Plintaquults (*Plintossolo Argilúvico Distrófico*), and Aquentes (*Gleissolo Háplico Alítico*) occur in low-lying areas (Schneider et al., 2008).

Available soil and terrain database

The Porto Alegre soil survey (Schneider et al., 2008), part of a comprehensive environmental assessment (Hasenack et al., 2008), covers the entire municipality and contains a soil map published at 1:50,000 scale. It is formed by twelve MUs: one single MU, one MU composed of terrain types, and ten multi-component MUs. Of these last MUs, nine are soil associations and one is an undifferentiated group.

The original 72-pedon dataset was obtained from the pedologists who carried out the original soil survey, and it was used as an information source in addition to the soil map. Pedon data included soil classification to the second categorical level of the Brazilian Soil Classification System (SiBCS), the geographical coordinates, slope, and landscape position of each pedon. A digital hypsometric map (line vector format with 1 m interval contours), from Hasenack et al. (2010), was used to produce a digital elevation model (DEM) with a 15-m pixel resolution with ArcMap™ 10.2 (ESRI, 2013).

Assignment of soil-landscape relationships and creation of training area

This methodology follows a rationale similar to that of Nauman et al. (2014), Nauman and Thompson (2014), and Sarmiento et al. (2017) (Figure 2). The initial effort was to select areas typifying the occurrence of each soil component, where there is high probability that a certain soil component will occur. Through selection of these areas, it was possible to correlate the environmental variables with the soil components and, using prediction models, to generate maps with MUs containing only single components.

The multi-component MUs used for disaggregation were CX, GX, PV1, PV2, and SG1 (Table 1), which occupy approximately 80 % of the municipal area. These MUs were chosen because the soil components that compose them occur in distinguishable positions in the landscape, as described in the survey report, thus enabling the individualization of each soil component to generate a map with the largest number of simple MUs. The areas of the MUs not used in the disaggregation were maintained within their original limits.

First, we attempted to identify the most typical environmental conditions for each soil class present in the MU. The soil survey report provided initial information on slope and landscape position for the soil classes. A slope map and a landform map were created with the DEM in ArcMap™ 10.2 and LandMapR (MacMillan, 2003), respectively, to obtain

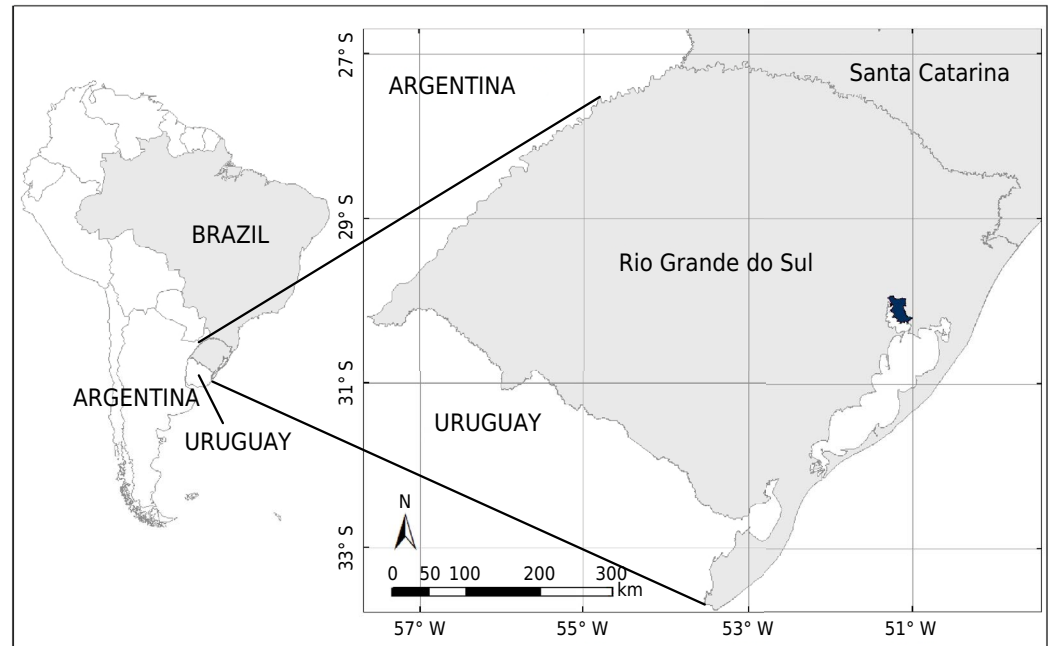


Figure 1. Location of the study area in the state of Rio Grande do Sul, Brazil.

the slope and the landscape position of each pedon. LandMapR produces landscape segmentation (into 15 landforms) based on elevation, surface contours, slope length, relative slope position, and other variables (MacMillan et al., 2000; MacMillan et al., 2005; Sarmiento et al., 2017). The relation between LandMapR and the landforms and the landscape position of each soil component was established by comparing the description of each landform provided by MacMillan (2003) and the description of the position occupied by each soil component in the landscape, which is contained in the soil survey report (Schneider et al., 2008).

After that, the pedons were cross-tabulated with the slope and landform maps and the soil map containing the delimitations of the MUs to generate a table with the combination of these three variables. Analyzing the combinations, we noted that the slope variable did not contribute to explain the occurrence of soil components commonly found at lower elevations, which have poorly drained soils, such as Aquepts, Albaquults, and Plintaquults. Therefore, it was necessary to include an additional environmental variable, the Topographic Wetness Index (TWI). This index, developed by Beven and Kirkby (1979), combines the upslope contributing area and slope to explicitly quantify topographic control over hydrological processes (Sørensen and Seibert, 2007). The index was generated in ArcMap. A cross-tabulation of poorly drained soil pedons and TWI was conducted and showed high correlation between these soils and this variable. Earlier studies by Giasson et al. (2006) and Nauman et al. (2014) also used the TWI to differentiate areas with contrasting drainage in DSM studies. Subsequently, the study was conducted separately in two subareas: MUs containing well-drained soils (WDS) and imperfectly/poor drained soils (IPDS).

The most common combinations between MU, slope, and landform were selected for the WDS areas, and the most common combinations between MU, TWI, and landform were selected for the IPDS areas. From these combinations, rules that explain the occurrence of soil components were created. For example: Inceptisols are expected to occur on a Divergent Backslope (DBS) landform with slopes ranging from 23-30 % in the multi-component MU CX. Aquepts are expected to occur in a Toe Slope (TSL) landform with TWI ranging from 10 to 15 in the multi-component MU GX. For each soil component, not only one, but several individual rules were created. At the end of the rule creation process for a total of six different individualized soil components, a total of 210 unique soil occurrence rules were created (Table 2).

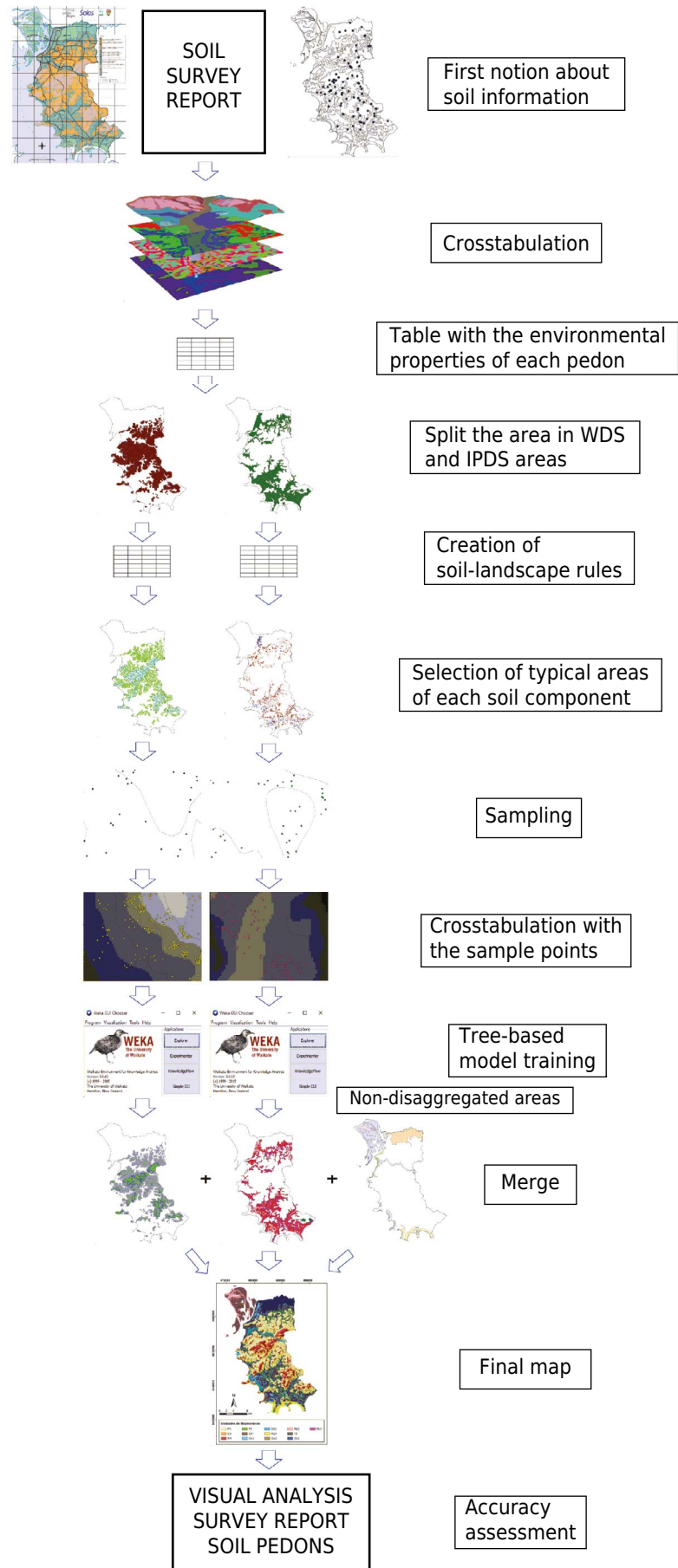


Figure 2. Schema of methodological steps for disaggregating soil map units in the Porto Alegre municipality area.

Table 1. Soil map units in the Soil Survey map of Porto Alegre, RS, Brazil (adapted from Schneider et al., 2008)

Map unit		Drainage ⁽¹⁾	Soil Taxonomy		Brazilian System		Area %
ID	Type		Principal	Inclusions	Principal	Inclusions	
PV1	Undifferentiated Group	WDS	Ultisols	Inceptisols Lithic Udorthents	<i>Argissolos</i>	<i>Cambissolos</i> <i>Neossolo</i> <i>litólico</i>	6.9
PV2	Association	WDS	Ultisols and Inceptisols	Lithic Udorthents	<i>Argissolos and</i> <i>Cambissolos</i>	<i>Neossolo</i> <i>litólico</i>	15.8
CX	Association	WDS	Inceptisols and Lithic Udorthents	Ultisols Rocky outcrops	<i>Cambissolos and</i> <i>Neossolo Litólico</i>	<i>Argissolos</i> <i>Afloramentos</i> <i>rochosos</i>	14
SG1	Association	IPDS	Albaquults, Aquentes, and Plintaquults	-	<i>Planossolo Háplico,</i> <i>Gleissolo Háplico, and</i> <i>Plintossolo Argilúvico</i>	-	26.8
SG2	Association	NU	Albaquults, Aquentes, and Fluvents	-	<i>Planossolo Háplico,</i> <i>Gleissolo Háplico,</i> <i>and Neossolo Flúvico</i>	-	1.9
GX	Association	IPDS	Aquentes and Albaquults	-	<i>Gleissolo Háplico</i> <i>and Planossolo</i> <i>Hidromórfico</i>	-	14.6
G1	Association	NU	Aquentes and Fluvents	Histosols	<i>Gleissolo Háplico and</i> <i>Neossolo Flúvico</i>	<i>Organossolos</i>	7.4
G2	Association	NU	Aquentes and Albaquults and Terrain Types ⁽²⁾	Plintaquults	<i>Gleissolo Háplico,</i> <i>Planossolos, and</i> <i>Tipos de Terreno</i> ⁽²⁾	<i>Plintossolo</i> <i>Argilúvico</i>	6.3
RQ	Association	NU	Quartzipsamments and Aquentes	-	<i>Neossolo</i> <i>Quartzarênico and</i> <i>Gleissolo Háplico</i>	-	2.5
RU1	Simple	NU	Fluvents	Aquentes	<i>Neossolo Flúvico</i>	<i>Gleissolo</i> <i>Háplico</i>	0.1
RU2	Association	NU	Fluvents and Terrain Types	Aquentes	<i>Neossolo Flúvico and</i> <i>Tipos de Terreno</i>	<i>Gleissolo</i> <i>Háplico</i>	2.1
TT	Terrain Type	NU	-	-	<i>Tipos de Terreno</i>	-	1.6

⁽¹⁾ Drainage classes created in this study. WDS = well-drained soil area; IPDS = imperfectly/poorly drained soil area; NU = not used for disaggregation; - = no inclusions. ⁽²⁾ Terrain types (*Tipos de Terreno*) are map units with few or none natural soil (IBGE, 2015).

These rules were translated into logical expressions for insertion into the ArcMap's Raster Calculator tool. Areas corresponding to the rule combinations of landform, MU, and slope (for the WDS areas) or landform, MU, and TWI (for the IPDS areas) were selected, aiming to represent the typical areas for each soil component (Figure 2). After selection, these typical areas were converted to polygon vector format to facilitate the creation of sample points that were needed for the predictive model. Sample points were created in ArcMap™ 10.2 with the Sampling Design Tool (Buja and Menza, 2013). We used a stratified random sampling approach in which a given point density was defined and applied to all polygons, resulting in similar density for all the polygons of the training area. This approach allowed better distribution of points across polygons, as opposed to random sampling, which tends to provide greater density of points in large polygons, thus reducing the importance of the information contained in small polygons (Odgers et al., 2014). The point density chosen was approximately 2.5 points per hectare, as suggested by Sarmiento et al. (2012) and Bagatini et al. (2015) for sampling density in DSM. The sampling process resulted in selection of approximately 50,000 sampling points in the WDS area and approximately 38,000 sampling points in the IPDS area for use in the predictive model.

Table 2. Examples of rules created to describe the typical location of soil components within the five mapping units based on the slope ranges, landforms, and Topographic Wetness Index (TWI)

Mapping unit	Slope range	Landform	TWI	Soil component
	%			
		WDS area		
PV1	<20	Any	-	Ultisol
	20-45	DSH	-	Inceptisol
	>45	Any	-	Lithic Udorthents
PV2	<3	TSL, TER	-	Ultisol
	3-8	FSL	-	Ultisol
	8-20	BSL	-	Inceptisol
	>45	DSH	-	Lithic Udorthents
CX	<3	LCR, TER	-	Ultisol
	8-20	FSL, TSL, FAN	-	Ultisol
	8-20	BSL, DBS, CBS	-	Inceptisol
	Any	DSH	-	Lithic Udorthents
		IPDS area		
SG1	-	TSL	7-9	Plintaquults
	-	TSL	9-11	Albaquults
	-	TSL	>11	Aquents
GX	-	BSL, TSL	9-11	Albaquults
	-	TER, TSL	>11	Aquents

DSH = divergent shoulder; TSL = toe slope; TER = terrace; FSL = foot slope; BSL = back slope; LCR = level crest; FAN = lower slope fan; DBS = divergent back slope; CBS = convergent back slope; Any = any of the landforms; - = not applicable to this MU.

Tree-based model implementation

To implement the predictive model, a set of 32 environmental variables (Table 2) was generated in SAGA-GIS (Conrad et al., 2015) from the DEM. These variables were then cross-tabulated in ArcMap with the sampling points from the previous step. In this step, each sampling point received a combination of values from the variables. The process generated two tables, one for the WDS area and one for the IPDS area. These tables were inserted in the data-mining software WEKA 3.6 (Hall et al., 2009) and formed the database for implementation of the predictive models for generation of the disaggregated soil map. With the Attribute Selection function of WEKA, the variables were tested for their contribution to soil component mapping in the predictive model. Based on statistical analysis of the dataset, this tool searched which subset of properties worked best for prediction. Then, relevant properties could be selected, and the redundant or irrelevant ones could be discarded, resulting in a model that was simpler, faster, and easier to interpret (Hall and Holmes, 2003).

The predictive model chosen was the decision tree algorithm J48, which is a Java implementation of the C4.5 algorithm (Quinlan, 1993) in the WEKA data-mining tool. The choice was based on the satisfactory results shown by this algorithm in other DSM studies (Giasson et al., 2011; Costa, 2016). Pruning of the decision tree was established to avoid overfitting of the model; thus, terminal nodes with less than 10 pixels were suppressed. Values of 5, 15, 20, and 30 pixels were tested, but the value of 10 was chosen because it resulted in a predictive model with accuracy higher than 90 % without an excessive, time-consuming number of rules. Model training was performed with 50 % of the points, while the other half was used for validation.

The resulting tree-based models, one for the WDS area and the other for the IPDS area, were implemented using the Raster Calculator in ArcMap™ 10.2. This step generated two soil maps, one with only the soils of the WDS area and another with only the soils of the IPDS area. These two maps were merged with the areas that were not disaggregated to form one final soil map with approximately 80 % of its area containing individual soil components.

Map accuracy assessment

The accuracies of the original and disaggregated soil maps were assessed by intersecting the maps with the georeferenced pedon dataset (Häring et al., 2012; Nauman et al., 2014; Nauman and Thompson, 2014; Sarmiento et al., 2017). A 30-m circular buffer was created in each pedon, similar to that performed by Sarmiento et al. (2014), Nauman and Thompson (2014), Heung et al. (2016), and Vincent et al. (2018). This buffer is created for the purpose of disregarding the precision error involved in the GPS equipment used to collect the geographic coordinates of the pedons, which may be more than 20 meters in some cases, depending on the atmospheric conditions and the equipment used. The prediction was computed correctly when any pixel in the buffered area matched that of the reference pedon (Smith et al., 2012; Nauman and Thompson, 2014; Sarmiento et al., 2017).

The risk of a biased validation using the soil pedons was deemed low because their spatial location was not used directly as a training area. The pedons were used as an information source about the environmental conditions that each soil component occurs, aiming to create soil-landscape rules for selecting typical areas of each soil component. These selected areas, here called “training areas”, were used for training the tree-based model. The use of these pedons for validation helped attain one of our objectives, namely to reduce costs on field trips in elaborating a soil survey.

RESULTS AND DISCUSSION

A visual comparison between the original map and the disaggregated map provides a first assessment of the improvement obtained from MU disaggregation (Figure 3). Whereas in the original map each MU was composed of more than one soil component, in the disaggregated map, each MU is formed by only one. Unlike the original map in which lines delimit the MUs, the disaggregated map represents the distribution of MUs through pixels, enabling more gradual and continuous transitions between the MUs, as occurs in the landscape. In addition, the pixels may represent the inclusions, unlike the original map of polygons, in which it would not be possible to know their location. Thus, the disaggregated map provides more detailed information on soil components.

The disaggregated map had 80.5 % correct predictions, higher than the 79.2 % verified in the original map (Table 3). However, it should be noted that maps with several soil components composing each MU, such as the original map, tend to increase the rate of correct predictions, because they enable more than one soil component to be matched with a validation pedon. Sarmiento et al. (2017) verified correct predictions ranging from 45.5 to 48.5 % using a one-pixel buffer (30 m) for validation, but the intention of these authors was mapping up to the sixth categorical level of the SiBCS, which involved a higher number of components. Vincent et al. (2018) achieved 41 to 72 % correct predictions in disaggregation of a Brittany (France) soil map containing 341 MUs, although their legacy soil data were much more detailed than ours. In mapping soils in the USA within the Soil Taxonomy series (Soil Survey Staff, 2014), Nauman et al. (2014) obtained 69.8 % and Nauman and Thompson (2014) 39 to 44 % correct predictions; the latter authors used a 60 m buffer validation.

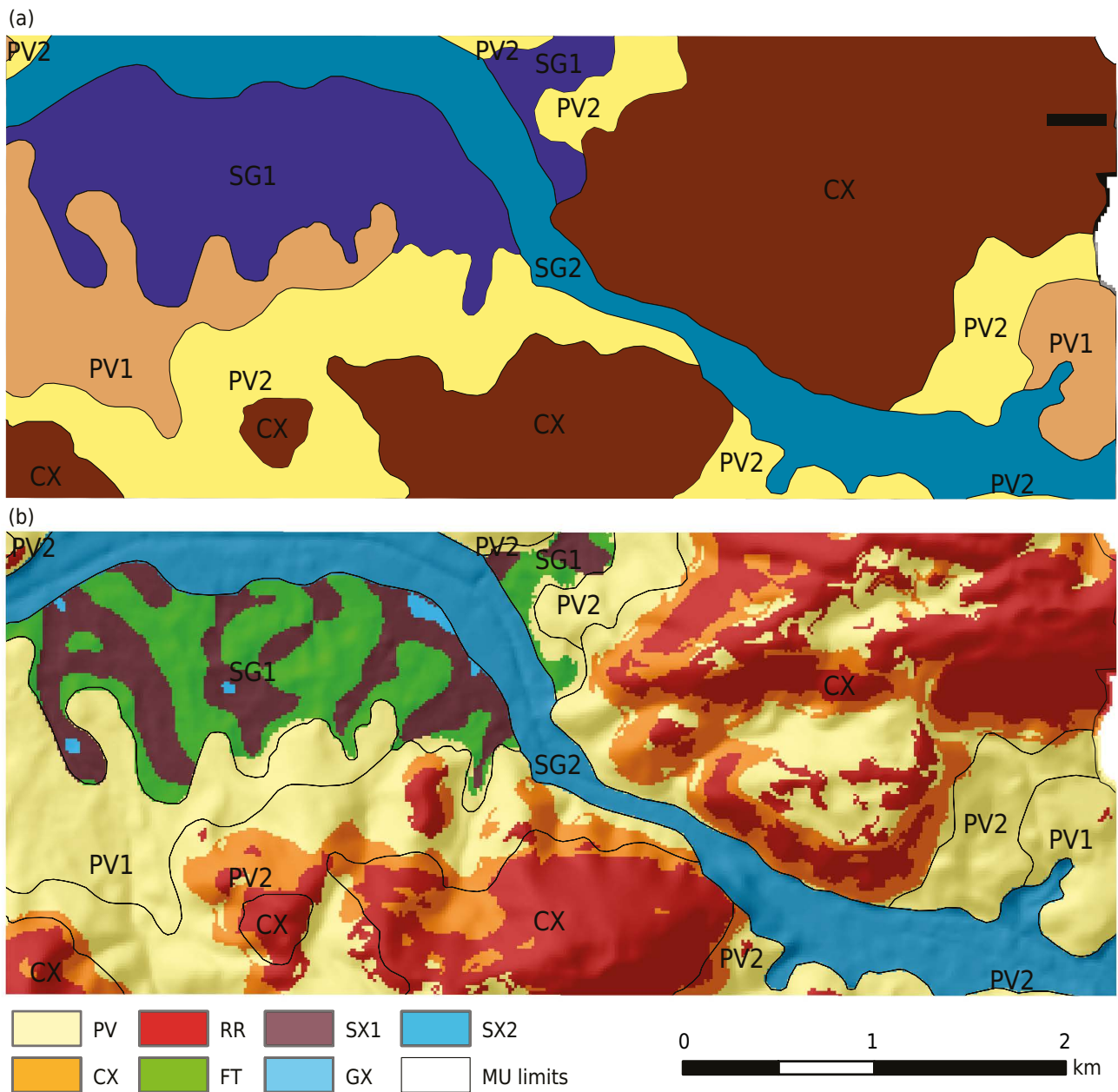


Figure 3. Comparison of a part of the original (a) and of the disaggregated (b) soil map. The acronyms in the images and in the legend correspond to the map units of the original and of the disaggregated soil map, respectively.

Soil components which had more georeferenced pedons available showed higher performance, similar to that verified by Häring et al. (2012), with 89.1, 81.8, and 75.0 % correct predictions for the MUs (single component) of PV, RR, and SX, respectively. The MU FT exhibited 100 % correct predictions, but the availability of only one pedon imposes only two possible results, 0 or 100 %, making it difficult to evaluate the real value of correct predictions. Aside from this exception, components with low availability of georeferenced points had the worst concordances, at 0 and 50 % for Inceptisols and Aquepts, respectively. These results reflect the difficulty of creating soil-landscape rules from a limited amount of information about the environmental conditions in which a given soil component occurs.

In the WDS areas, the disaggregated map showed an extensive area mapped with Ultisols, followed by Lithic Udorthents at the tops and steep slopes of hills (Figure 3). Even in the original MU CX, the Ultisols occupied an extensive area, in contrast with the report of the original soil survey (Table 1), which suggests that Inceptisols and Lithic Udorthents

Table 3. Variables tested in the decision tree algorithm

Tested variable	Used ⁽¹⁾	Tested variable	Used ⁽¹⁾
Catchment area	NU	Negative Openness	WDS
Catchment slope	NU	Normalized Height	NU
Channel Network Base Level	NU	Plan Curvature	NU
Closed Depressions	NU	Positive Openness	NU
Convergence Index	NU	Profile Curvature	NU
Cross-Sectional Curvature	NU	Relative Slope Position	NU
Flow Accumulation	IPDS	Slope	WDS
Digital Elevation Model	WDS	Slope Height	WDS
Landform	WDS, IPDS	Standardized Height	NU
Longitudinal Curvature	WDS	Terrain Ruggedness Index	NU
LS Factor	WDS	Texture	NU
Maximal Curvature	NU	Topographic Position Index	WDS, IPDS
Mid-Slope Position	NU	Topographic Wetness Index	WDS, IPDS
Modified Catchment Area	NU	Valley Depth	NU
Multi-resolution Ridge Top Flatness	WDS	Vector Terrain Ruggedness	NU
Multi-resolution Index of Valley Bottom Flatness	WDS	Vertical Distance to Channel Network	WDS

⁽¹⁾ WDS = well-drained soil area; IPDS = imperfectly/poor drained soil area; NU = variable not used, discarded by Weka's Attribute Selection function.

predominate in this MU. However, unlike the original survey, recent studies have shown that Inceptisols tend to occur under very specific topographic conditions, occupying narrow bands between Ultisols and Lithic Udorthents. In a study of the soils of Extrema Hill, in Porto Alegre, Medeiros et al. (2013) described the occurrence of Ultisols in places where the soil-landscape relationship would suggest the presence of Inceptisols, indicating that in the region, these soils occupy narrow zones of transition between Ultisols and Lithic Udorthents. Along the toposequence studied, these authors described the occurrence of three Ultisols, one Lithic Udorthent, and no Inceptisol. In the same municipality, Medeiros (2014) analyzed two toposequences, one in Santana Hill and one in São Pedro Hill, and found four Ultisols, two Lithic Udorthents, and two Inceptisols, indicating a higher probability of Ultisols in WDS areas. These findings reinforce the accuracy results of our study and the understanding that the disaggregated map seems to be closer to reality since it shows a greater presence of Ultisols in areas where Inceptisols could theoretically be suggested.

However, although the disaggregated map improved correspondence to the presence of Ultisols, the Inceptisols (CX) exhibited 100 % error. In this map error, the four points corresponding to this component were located in pixels referring mainly to the Ultisols. This mistake is a combined result of the low availability of Inceptisol pedons, associated with the fact that these two soil components occupy similar landscape positions; they occur in similar slopes and positions in the terrain, as stated in the field report. This resulted in difficulty in creating refined rules for the Inceptisols and, consequently, their prediction by the model. This difficulty could be overcome if a higher number of Inceptisol pedons had been available, which would help refine the rules for selecting the typical areas of this component, thus improving agreement of the prediction map with the georeferenced pedons.

The average accuracy of the IPDS areas was 72.7 %, and was 100, 75, and 50 % for the Plintaquults, Albaquults, and Aquents, respectively (Table 4). These accuracies were satisfactory, considering the greater difficulty in mapping these areas in comparison to better drained areas because of the significant heterogeneity of soils inherent to hydromorphic environments (Coringa et al., 2012; Guimarães et al., 2013; Silva Neto, 2015). Moreover, the terrain variations are small in these areas, which makes it more difficult to differentiate soil classes using terrain variables. This difficulty in mapping is also evident from visual analysis of the original soil map, where the polygons of the MU are large and have simple shapes; this may indicate difficulty of pedologists in delineating the MU in these areas. Höfig et al. (2014) used DSM and reported difficulty in mapping low elevation areas, which was overcome with division of the study area into units with homogeneous landscape according to its drainage pattern.

The accuracies obtained in our disaggregated map demonstrated the ability of the predictive model to represent the soil distribution in the landscape, which is our purpose. This was possible because the areas typifying the occurrence of each component, selected for training the tree-based model, were representative of reality. So, this leads us to affirm that creation of the rules relating soil components to their environments must have been efficient, which is largely a result of the effectiveness of the variables used in this step, i.e., landform, TWI, and slope. Sarmiento et al. (2017) also used the landform and slope variables to translate indication of the position in which a given soil component occurs in a toposequence, which helped these authors in the disaggregation of a soil map from a mountainous region in southern Brazil. Nauman et al. (2014) used TWI to identify typical drainage patterns of certain soil components within the MUs and perceived an important relationship with aerial photographs. This enabled selection of typical areas for training a predictive model for spatial disaggregation of a soil map in Arizona, USA. Giasson et al. (2006) also used this variable for selecting reference areas based on drainage classes. Similarly, in our study we verified the noteworthy contribution of these variables in identifying the typical occurrence of soil components within MU, which recommends their inclusion in future DSM applications.

The approach used in this study adequately disaggregated multi-component MUs into their soil components in the study area and produced a more detailed soil map. It may be applied under circumstances of soil surveys with limited detail and available information. Considering that many of the soil surveys available in Brazil have characteristics like those studied here, this approach is a promising alternative for generating maps more suitable to current demands in Brazil.

Table 4. Soil component and disaggregated map accuracies, assessed by the intersection with the available pedons

Map unit	Soil component	Validation points ⁽¹⁾	Correct ⁽²⁾	Correct %
PV	Ultisol	46	41	89.1
CX	Inceptisol	4	0	0.0
RR	Lithic Udorthents	11	9	81.8
FT	Plintaquults	1	1	100.0
SX	Albaquults	8	6	75.0
GX	Aquents	2	1	50.0
Disaggregated soil map		72	58	80.5
Original soil map		72	57	79.2

⁽¹⁾ A 72-pedon dataset available. ⁽²⁾ The prediction was considered correct whenever any pixel in a 30-meter radius matched that of the reference pedon.

CONCLUSIONS

The methodology presented in this study proved useful in producing a more detailed map by disaggregating multi-component map units into single-component map units.

The terrain variables of Landform, Slope, and Topographic Wetness Index were useful in distinguishing some sites for occurrence of the soil components and they can be used as a support in identifying typical areas for training predictive models.

The methodology is promising for application in areas with a similar amount and type of data available.

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