

## A wavelet-based method for power-line interference removal in ECG signals

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**Abstract Introduction:** The analysis of electrocardiogram (ECG) signals allows the experts to diagnosis several cardiac disorders. However, the accuracy of such diagnostic depends on the signals quality. In this paper it is proposed a simple method for power-line interference (PLI) removal based on the wavelet decomposition, without the use of thresholding techniques. **Methods:** This method consists in identifying the ECG and noise frequency range for further zeroing wavelet detail coefficients in the subbands with no ECG coefficients in the frequency content. Afterward, the enhanced ECG signal is obtained by the inverse discrete wavelet transform (IDWT). In order to choose the wavelet function, several experiments were performed with synthetic signals with worse Signal-to-Noise Ratio (SNR). **Results:** Considering the relative error metrics and runtime, the best wavelet function for denoising was Symlet 8. Twenty synthetic ECG signals with different features and eight real ECG signals, obtained in the Physionet Challenge 2011, were used in the experiments. Results show the advantage of the proposed method against thresholding and notch filter techniques, considering classical metrics of assessment. The proposed method performed better for 75% of the synthetic signals and for 100% of the real signals considering most of the evaluation measures, when compared with a thresholding technique. In comparison with the notch filter, the proposed method is better for all signals. **Conclusion:** The proposed method can be used for PLI removal in ECG signals with superior performance than thresholding and notch filter techniques. Also, it can be applied for high frequencies denoising even without a priori frequencies knowledge.

**Keywords** Power-line interference, Denoising ECG signals, Wavelet decomposition.

## Introduction

ECG signals represent the heart electrical activity and they are obtained through electrodes placed in specific regions of the human body. There are five main waves characterizing ECG signals: P, Q, R, S, and T. Each wave or complex has an exclusive significance. The combination of Q, R and S waves forms which is known as QRS complex. The P wave and the QRS complex represent the atrial and ventricular depolarization, respectively. On the other hand, the T wave characterizes

the ventricular repolarization. The spectrum of the QRS complex is located in the ECG frequency bands whose typical frequency components range from 10 Hz to 25 Hz (Köhler et al., 2002) and its detection is still subject of many studies. Pan and Tompkins (1985) developed an objective QRS detection algorithm using a band-pass filter from 5 Hz to 12 Hz. Zidelmal et al. (2012) computed the power spectrum for four QRS types concluding that their energies are concentrated in the range from 5 Hz to 22 Hz. Such spectral information is used to QRS complexes detection in Challenge 2011 (Training Set A) database (Oliveira et al., 2015). In addition, it is important to remark that ECG signals are non-stationary, non-symmetric in relation to the *x*-axis and are originally impulsive signals (Łeński and Henzel, 2005).

The specific morphology of the ECG signals allows identifying various cardiac diseases. However, for an accurate analysis, signals should have high Signal-to-Noise Ratio (SNR) (Łeński and Henzel, 2005). Low SNR can difficult the analysis performed by experts or computational applications, since it changes the signal waveform. Typical noise present in ECG signals are due to power-line



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interference in a frequency band varying from 50 Hz to 60 Hz (Łęski and Henzel, 2005; Patil and Chavan, 2012; Rahman et al., 2010) depending on the country. It occurs due to interferences of electrical equipment as X-ray, air conditioners, elevators (Patil and Chavan, 2012), and also due to the differences in electrode impedances (Bahoura and Ezzaidi, 2010).

Several researchers have proposed denoising approaches to enhance ECG signals and preserve their original characteristics. Some noise reduction techniques are based on digital filters, wavelet transform and adaptive filtering (AlMahamdy and Riley, 2014); singular value decomposition (Bandarabadi and Karami-Mollaei, 2010); independent component analysis (Phegade and Mukherji, 2013) and S-transform (Das and Ari, 2013). Among the algorithms for PLI removal there are digital processing methods based on: fuzzy thresholding (Üstündağ et al., 2012); nonlinear filter bank (Łęski and Henzel, 2005); Fast Fourier Transform and adaptive nonlinear noise estimator (Shirbani and Setarehdan, 2013); Empirical Mode Decomposition (Agrawal and Gupta, 2013); neural networks (Mateo et al., 2008) and wavelet transform (Agrawal and Gupta, 2013; Garg et al., 2011; Poornachandra and Kumaravel, 2008; Rahman et al., 2010).

Wavelet analysis has been successfully used for ECG signal denoising because it deals well with non-stationary signals and also presents better resolution in time-frequency domain than Fourier analysis (Rahman et al., 2010). In the comparative study presented by AlMahamdy and Riley (2014), the wavelet transform produced better results in most of the experiments. Chouakri et al. (2006) compared the performance of Butterworth filters and the multilevel wavelet transform, concluding that improved results were achieved by the wavelet technique. Usually, wavelet-based methods for ECG denoising use thresholding techniques with some additional processing (Agante and Sa, 1999; AlMahamdy and Riley, 2014; Awal et al., 2014; Bahoura and Ezzaidi, 2010; Chouakri et al., 2006; Garg et al., 2011; Germán-Salló, 2010; Karthikeyan et al., 2012; Li et al., 2009; Patil and Chavan, 2012; Poornachandra and Kumaravel, 2008; Üstündağ et al., 2012). Patil and Chavan (2012) compared the PLI removal for different wavelet basis using hard and soft shrinkage functions. They conclude that hard thresholding achieves better SNR scores than soft thresholding, and the best wavelet basis depends on the analyzed signal.

Garg et al. (2011) worked on optimal wavelet-based algorithm for ECG denoising, analyzing SNR for several wavelet families, decomposition level and threshold selection method. In order to calculate the threshold, four rules were used: min-max, rigorous sure, universal and heuristic sure. The best configuration was achieved with the Symlet wavelet with ten vanishing moments

and five decomposition levels, hard shrinkage function and heuristic sure rule or rigorous sure thresholding. Poornachandra and Kumaravel (2008) proposed to use of hyper shrinkage function in the subbands that contained the PLI noise at some decomposition level. The obtained results were better when compared to those of the state-of-the-art algorithms.

In this paper, it is proposed to use discrete wavelet transform (DWT) to decompose an ECG signal degraded by high power-line interference. The goal is to have the ECG signal represented by the approximation coefficients and the noise by the detail coefficients. The basic idea is to inspect the ECG and noise frequency range in each subband of the wavelet filter bank. The wavelet scale whose frequency range exceeds the maximum frequency of the ECG signals is set to zero. Then, the IDWT is applied in order to obtain a better quality signal without the use of thresholding techniques. It is common that such techniques do not completely eliminate noise, generating residual noise that can still distorts the QRS waveform. Therefore, this original ECG analysis methodology eliminates the need of thresholding function and is based solely on wavelet filter bank and the characteristics of PLI. Comparisons with a thresholding technique and a classical digital filter were carried out to demonstrate the effectiveness of the proposed method. Furthermore, the proposed method presents low computational load, reduces the residual noise and can be easily implemented.

## Methods

A noisy ECG,  $s(t)$ , contaminated by PLI can be represented as follows:

$$s(t) = x(t) + \alpha \cos(2\pi f_r t + \varphi), \quad (1)$$

where  $t$  is time and  $f_r = 50$  Hz or  $f_r = 60$  Hz is the PLI frequency. The unknown parameters are  $\varphi \in [0, 2\pi]$ , PLI signal phase and  $\alpha > 0$ , the amplitude. The clean ECG is represented by  $x(t)$ .

### *Dynamical model for generating synthetic ECG signals*

In order to analyze ECG denoising algorithms performances, many metrics based on comparisons between the estimated signal and the original one have been proposed. Real ECG signals may have other noise besides PLI. To focus only on this kind of noise, synthetic ECG signals are used in some experiments. The mathematical model for generating such signals was given by McSharry et al. (2003). They proposed a dynamical model that generates a trajectory in the three-dimensional state-space given by three coupled ordinary differential equations (ODE). The displacement

around the “attracting limit cycle of unit radius” describes the ECG signal for each RR-interval (McSharry et al., 2003). ECG characteristic waves are events with fixed angles in relation to the unit circle, given by  $\theta_i$ , for  $i \in \{P, Q, R, S, T\}$ . The ODE model (McSharry et al., 2003) is given by  $\dot{y} = (1 - \sqrt{x^2 + y^2})y + \rho x$ ,  $\dot{x} = (1 - \sqrt{x^2 + y^2})x - \rho y$  and  $\dot{z} = -\sum_i \Delta\theta_i \exp\left(-\frac{\Delta\theta_i^2}{2b_i^2}\right) - [z - 0.15 \sin(2\pi f_2)]$ , where  $\theta = \text{atan2}(x, y)$  and  $\text{atan2}(x, y)$  is the element-by-element arctangent between  $x$  and  $y$  arrays,  $\Delta\theta_i = (\theta - \theta_i)$ ,  $\rho$  is the angular trajectory velocity and  $f_2$  is the respiratory frequency for modeling the baseline wander.  $z$  is the generated ECG itself.

This dynamical model yields realistic signals when compared to real ECG signals (McSharry et al., 2003). By setting parameters  $a_i, b_i, \theta_i$  and  $f_2$ , different morphologies can be generated for ECG characteristic waves. Note that  $z$  is a superposition of sinusoidal and Gaussian functions. Therefore, parameters  $a_i$  and  $b_i$  affect the amplitude and the width of the simulated ECG waves, respectively.

Some specific features of the heart rate can also be set, such as mean and standard deviation, besides spectral properties. Generated waveforms are similar

to the 12-lead ECG lead I. Although it is possible to produce multi-lead signals (McSharry et al., 2003), in this work they were not considered.

In order to set parameters of the proposed method and perform experiments for validation, twenty synthetic signals were generated using the described model. Model parameters and features of the generated ECG signals are summarized in Table 1 and Table 2. All signals were sampled at  $f_s = 500$  Hz, in an interval of 60 seconds (30001 samples). Parameters were set for the dynamical model in order to obtain ECG signals with different heart rate, SNR and PLI values. By using different settings, it was possible to obtain ECG waveforms with different lengths, amplitudes and fiducial points. Noise was added to each synthetic signal according to equation (1), considering the parameters described in Table 1 and Table 2. Such parameters simulate different PLI noises which can be found in a real ambulatory (Huhta and Webster, 1973), unlike the most state-of-the-art methods which focus on pure sinusoidal noise. So, in addition to the fundamental frequency, harmonics interferences were also considered (Costa and Tavares, 2009).

**Table 1.** ECG synthetic signals configuration using the model described in this section. Parameters:  $f_r$  is PLI frequency;  $\varphi$  and  $\alpha$  are noise phase and noise amplitude, respectively; other parameters refer to the dynamical model.

Variable	$s_1$	$s_2$	$s_3$	$s_4$	$s_5$	$s_6$	$s_7$	$s_8$	$s_9$	$s_{10}$
Signal										
<b>bpm</b>	60	100	45	82	98	142	90	132	71	89
<b>SNR</b>	-9.9574	-6.1875	2.9491	-3.9308	10.6917	-18.7064	-6.3261	-11.3478	0.8604	-12.8859
<b><math>f_r</math> (Hz)</b>	50	60	50	60	50	60	120	100	50	60
<b><math>\varphi</math></b>	0	$\pi/4$	$2\pi/3$	$11\pi/180$	$-37\pi/180$	0	0	0	$63\pi/60$	$-57\pi/45$
<b><math>\alpha</math></b>	1.0	0.7	0.2	0.4	0.1	2.7	0.7	1.2	0.3	1.5
<b><math>\theta_P</math></b>	-1.2217	-1.3882	-1.1370	-1.3209	-1.3811	-1.5153	-1.3520	-1.4879	-1.2742	-1.3483
<b><math>a_P</math></b>	1.2	1.2	1.2	1.2	1.2	1.2	1.2	1.2	1.2	1.2
<b><math>b_P</math></b>	0.25	0.3227	0.2165	0.2922	0.3195	0.3846	0.3061	0.3708	0.2719	0.3044
<b><math>\theta_Q</math></b>	-0.2618	-0.3380	-0.2267	-0.3060	-0.3345	-0.4027	-0.3206	-0.3883	-0.2847	-0.3188
<b><math>a_Q</math></b>	-5	-5	-5	-5	-5	-5	-5	-5	-5	-5
<b><math>b_Q</math></b>	0.1	0.1290	0.0866	0.1169	0.1278	0.1538	0.1224	0.1483	0.1087	0.1217
<b><math>\theta_R</math></b>	0	0	0	0	0	0	0	0	0	0
<b><math>a_R</math></b>	30	30	30	30	30	30	30	30	30	30
<b><math>b_R</math></b>	0.1	0.1290	0.0866	0.1169	0.1278	0.1538	0.1224	0.1483	0.1087	0.1217
<b><math>\theta_S</math></b>	0.2618	0.3380	0.2267	0.3060	0.3345	0.4027	0.3206	0.3883	0.2847	0.3188
<b><math>a_S</math></b>	-7.5	-7.5	-7.5	-7.5	-7.5	-7.5	-7.5	-7.5	-7.5	-7.5
<b><math>b_S</math></b>	0.1	0.1290	0.0866	0.1169	0.1278	0.1538	0.1224	0.1483	0.1087	0.1217
<b><math>\theta_T</math></b>	1.7453	1.9831	1.6242	1.8870	1.9730	2.1647	1.9315	2.1256	1.8203	1.9261
<b><math>a_T</math></b>	0.75	0.75	0.75	0.75	0.75	0.75	0.75	0.75	0.75	0.75
<b><math>b_T</math></b>	0.4	0	0.3464	0.4676	0.5112	0.6153	0.4899	0.5933	0.4351	0.4871

**Table 2.** ECG synthetic signals configuration using the model described in this section. Parameters:  $f_r$  is PLI frequency;  $\varphi$  and  $\alpha$  are noise phase and noise amplitude, respectively; other parameters refer to the dynamical model.

Variable	$s_{11}$	$s_{12}$	$s_{13}$	$s_{14}$	$s_{15}$	$s_{16}$	$s_{17}$	$s_{18}$	$s_{19}$	$s_{20}$
<b>Signal</b>										
<b>bpm</b>	112	88	102	102	143	48	83	112	32	32
<b>SNR</b>	-26.6488	-24.5940	-7.2742	-12.2446	-30.4465	-20.9463	-18.0920	-25.9964	-25.2101	-21.3714
<b><math>f_r</math> (Hz)</b>	50	180	240	60	60	50	240	100	60	50
<b><math>\varphi</math></b>	$-37\pi/180$	0	0	$-57\pi/45$	$11\pi/180$	$-37\pi/180$	0	0	0	0
<b><math>\alpha</math></b>	7.2	5.8	0.8	1.4	10.4	3.3	2.7	6.9	4.7	3.1
<b><math>\theta_P</math></b>	-1.4280	-1.3444	-1.3950	-1.3950	-1.518	-1.1554	-1.3249	-1.4280	-1.0440	-1.0440
<b><math>a_P</math></b>	1.2	1.2	1.2	1.2	1.2	1.2	1.2	1.2	1.2	1.2
<b><math>b_P</math></b>	0.3415	0.3027	0.3259	0.3259	0.3860	0.2236	0.2940	0.3415	0.1825	0.1825
<b><math>\theta_Q</math></b>	-0.3576	-0.3170	-0.3413	-0.3413	-0.4042	-0.2341	-0.3079	-0.3576	-0.1911	-0.1911
<b><math>a_Q</math></b>	-5	-5	-5	-5	-5	-5	-5	-5	-5	-5
<b><math>b_Q</math></b>	-0.1366	0.1211	0.1304	0.1303	0.1544	0.0894	0.1176	0.1366	0.0730	0.0730
<b><math>\theta_R</math></b>	0	0	0	0	0	0	0	0	0	0
<b><math>a_R</math></b>	30	30	30	30	30	30	30	30	30	30
<b><math>b_R</math></b>	0.1366	0.1211	0.1304	0.1303	0.1544	0.0894	0.1176	0.1366	0.0730	0.0730
<b><math>\theta_S</math></b>	0.3576	0.3170	0.3413	0.3413	0.4042	0.2341	0.3079	0.3576	0.1911	0.1911
<b><math>a_S</math></b>	-7.5	-7.5	-7.5	-7.5	-7.5	-7.5	-7.5	-7.5	-7.5	-7.5
<b><math>b_S</math></b>	0.1366	0.1211	0.1303	0.1303	0.1543	0.0894	0.1176	0.1366	0.0730	0.0730
<b><math>\theta_T</math></b>	2.0400	1.9207	1.9929	1.9929	2.1685	1.6506	1.8928	2.0400	1.4915	1.4915
<b><math>a_T</math></b>	0.75	0.75	0.75	0.75	0.75	0.75	0.75	0.75	0.75	0.75
<b><math>b_T</math></b>	0.5465	0.4844	0.5215	0.5215	0.6175	0.3577	0.4704	0.5465	0.2921	0.2921

### Real ECG signals

In order to validate the proposed method using real ECG signals that have been originally corrupted by PLI, the Challenge 2011 (Training Set A) database from Physionet was chosen (Goldberger et al., 2000). Their records were sampled at 500 Hz with 16-bit resolution, during 10 seconds, for standard 12-lead (leads I, II, III, aVR, aVL, aVF, V1, V2, V3, V4, V5, V6) and their parameters are summarized in Table 3. Note from Table 3 that Power Spectral Density (PSD) column is the sum of the power spectrum density only for frequencies over 25 Hz, and it is expressed as  $PSD \times 10^4$  decibels (dB).

### Discrete wavelet transform

The wavelet analysis has been applied to various problems in biomedical engineering including noise removal in ECG signals (Agante and Sa, 1999; AlMahamdy and Riley, 2014; Awal et al., 2014; Bahoura and Ezzaidi, 2010; Chouakri et al., 2006; Garg et al., 2011; Germán-Salló, 2010; Karthikeyan et al., 2012; Li et al., 2009; Patil and Chavan, 2012; Poornachandra and Kumaravel, 2008; Üstündağ et al., 2012). Due to its better time-frequency resolution, it overcomes other classical methods, such as short time Fourier Transform, for instance (Üstündağ et al., 2012). One of the advantages when using wavelets is

the computational efficiency of Mallat’s pyramidal algorithm (Mallat, 1989). This algorithm is indeed a two-channel filter bank that splits the input signal in low and high frequencies by using quadrature mirror filters. The filters can be described through the wavelet  $\psi(t)$  and the scaling  $\phi(t)$  basis functions (Mallat, 1989):

$$\psi_{j,n}(t) = 2^{-j/2} \psi\left(\frac{t-2^j n}{2^j}\right), \tag{2}$$

$$\phi_{j,n}(t) = 2^{-j/2} \phi\left(\frac{t-2^j n}{2^j}\right), \tag{3}$$

$$h[n] = \langle 2^{-1/2} \phi(t/2), \phi(t-n) \rangle, \tag{4}$$

$$g[n] = \langle 2^{-1/2} \psi(t/2), \phi(t-n) \rangle, \tag{5}$$

where  $g[n] = (-1)^{1-n} h[1-n]$ ,  $j = 1, 2, \dots, J$  and  $n$  integer. Such basis functions satisfy the conditions  $\int |\phi(t)|^2 dt = 1$  (Mallat, 2009) and  $\int \psi(t) dt = 0$  (Daubechies, 1992). For a discrete analysis, wavelets are constructed by discretizing a “mother” function, and scaling it by  $2^j$  (Mallat, 2009), according to Equations (2) and (3). In this way, a signal  $x(t)$  is decomposed as follows (Mallat, 2009):

**Table 3.** Parameters of the real ECG signals.

Record (Lead)	eSQI	stdSQI	PSD (dB)
1007823 (II)	0.6460	0.2051	-1.5345
1034914 (III)	0.3982	0.1875	-1.2290
1086219 (III)	0.3969	0.2147	-1.3232
1098605 (V1)	0.4421	0.2969	-1.3742
1105115 (V2)	0.4136	0.1507	30.7853
1124627 (aVL)	0.5272	0.1676	-1.0693
2209843 (I)	0.5557	0.2565	-1.5421
1138505 (I)	0.4139	0.3344	-1.2085
<b>Average</b>	0.4742	0.2267	2.6881

$$d_j[n] = \langle x(t), \psi_{j,n}(t) \rangle \quad (6)$$

and

$$a_j[n] = \langle x(t), \phi_{j,n}(t) \rangle, \quad (7)$$

where  $a_j[n]$  and  $d_j[n]$  are, respectively, the  $j$ -th approximation and detail coefficients at scale  $2^j$ , and  $j$  is the decomposition level. In a general way, given two sequences  $f_1[n]$  and  $f_2[n]$ , their inner product is defined as  $\langle f_1, f_2 \rangle = \int f_1(t) \overline{f_2(t)} dt$ , where  $\overline{f_2(t)}$  is the complex conjugate of  $f_2(t)$ . These coefficients can be computed in a fast way by a cascade algorithm, using discrete convolutions and subsamplings, by means of  $a_{j+1}[p] = a_j * \overline{h}[2p]$  and  $d_{j+1}[p] = a_j[n] * \overline{g}[2p]$  (Mallat, 2009), where  $\overline{x}[n] = x[-n]$ ,  $p$  is an integer and  $*$  is the convolution operation. This operation means coefficients filtering in a lower resolution, i.e.,  $j$ . In this way,  $\overline{h}[2p]$  filters the higher frequencies and  $\overline{g}[2p]$  lets them pass. Therefore, an orthogonal representation for a signal  $x(t)$  is composed by the largest scale approximation coefficients plus detail coefficients at the scales  $j$  (Mallat, 2009), as follows:

$$x(t) = \sum_n a_j[n] \phi_{j,n}(t) + \sum_{j \leq J} \sum_n d_j[n] \psi_{j,n}(t). \quad (8)$$

Therefore, the wavelet decomposition output is a smooth signal representing the original one in a coarse way. In addition, the details are obtained when moving from a lower to a higher scale. Note that the smooth signal and details represent the similarity between the scaling and wavelet functions, according to Equations (7) and (6), respectively. For an ECG signal, the approximation coefficients represent its smoothed version. On the other hand, detail coefficients capture abrupt changes, such as high-frequency noises. In order to reconstruct the signal  $x(t)$  the following equation is required (Mallat, 2009):

$$a_j[p] = \overline{a}_{j+1} * h[p] + \overline{d}_{j+1} * g[p], \text{ where } \overline{y}[n] = 0 \text{ if } n = 2p+1 \text{ or } \overline{y}[n] = y[p] \text{ if } n = 2p.$$

In the analysis step, the output wavelet filter bank frequency spectrum is divided into two octave bands. In each new decomposition level, the low-frequency spectrum is again divided into two new octave bands, at the ideal cut-off frequencies, and so on, resulting in a logarithmical set of bandwidth (Germán-Salló, 2010). Therefore, if  $f_s$  is the sampling frequency, the frequency contents for approximation and detail coefficients, in the  $j$ -th decomposition level, are in the interval  $[0, f_s / 2^{j+1}]$  and  $[f_s / 2^{j+1}, f_s / 2^j]$ , respectively. In practice, the ideal cut-off frequencies are not realizable (Peng et al., 2009). Therefore, the intervals are not exactly those mentioned before. Abrupt changes in the frequency intervals do not occur, but the filters frequency responses magnitude decreases gradually, tending to a constant value. Thus, leakage energy affects the frequency content for each DWT decomposition subband. Approximation coefficients are scattered higher than  $f_s / 2^{j+1}$  frequencies. On the other hand, detail coefficients are lower than  $f_s / 2^{j+1}$  frequencies and higher than  $f_s / 2^j$ . Hence, there is a band overlap. Therefore, DWT frequency behavior impacts the decomposition level and the wavelet function choices. As an example, Figure 1 shows the frequency content for the quadrature mirror analysis filters given by Equations (2) and (3) for a 500 Hz sampling rate.

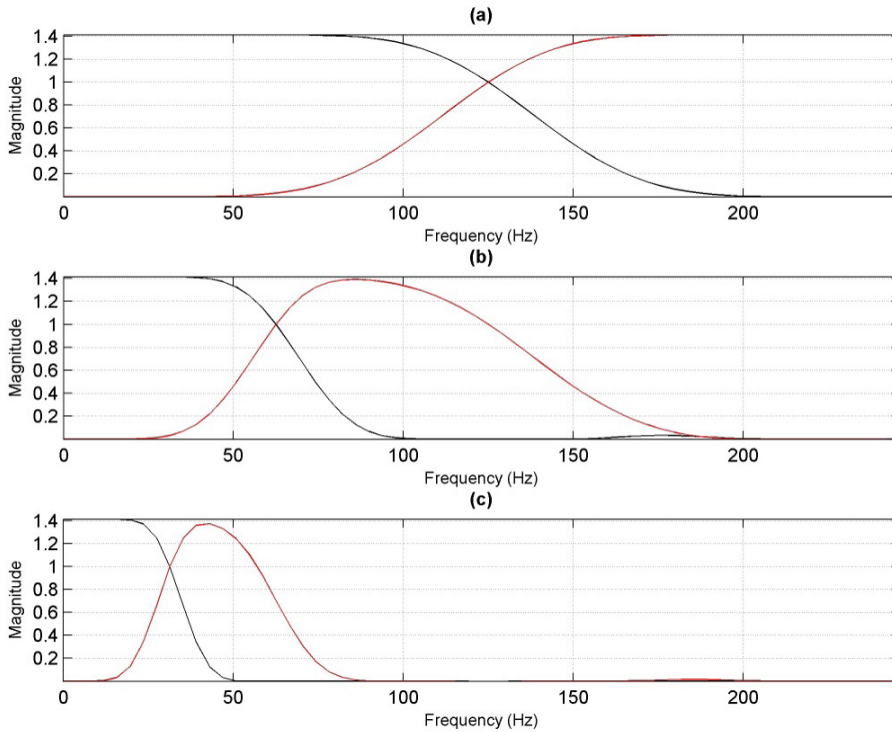
### Thresholding techniques

Classical methods for ECG denoising based on thresholding techniques present good performances (AlMahamdy and Riley, 2014; Garg et al., 2011; Patil and Chavan, 2012; Poornachandra and Kumaravel, 2008). Basically, in such methods, the goal is to estimate the signal  $x(t)$  from a contaminated signal  $s(t) = x(t) + r(t)$ , where  $r(t)$  is the additive noise (Donoho and Johnstone, 1994). For this purpose, the DWT is applied to  $s(t)$  and then  $d_j[n] = \langle s(t), \psi_{j,n}(t) \rangle$  in the wavelet domain is obtained. For hard shrinkage function, the absolute value of  $d_j[n]$  is compared to a threshold  $\lambda$ . If  $|d_j[n]| \leq \lambda$ , the corresponding value associated to the index  $n$  is set to 0. Otherwise, it is preserved.

In order to implement the wavelet shrinkage method, it has considered the Symlet 8 wavelet with three DWT decomposition levels and universal threshold (given by  $\lambda = \sqrt{2 \log(N)}$ , where  $N$  is the signal length), combined with hard thresholding function. It is noteworthy that this is the best configuration for this method (Garg et al., 2011; Patil and Chavan, 2012). The choice of the wavelet function order and the number of decomposition levels are justified since they are the same used by the proposed method.

### Notch filter

McManus et al. (1993) present four categories of digital filters for PLI removal: low-pass, notch-rejection, adaptive and global. For the implementation of the



**Figure 1.** Frequency response for the quadrature mirror analysis filters in Equations (2) (black line) and (3) (red line) for Symlet 8-tap wavelet in three decomposition levels and 500 Hz sampling rate. (a) Level one. (b) Level two. (c) Level three.

narrow-band-rejection filter (notch) it is considered a recursive filtering that includes a two-pole and two-zero filter. The filter output is given by  $y(k) = x(k) + a_1x(k-1) + a_2x(k-2) + a_3y(k-1) + a_4y(k-2)$  where  $x(k)$  is the input ECG signal and the coefficients are  $a_1 = -2(1 - \pi BC / f_s) \cos(\theta)$ ,  $a_2 = (1 - \pi BC / f_s)^2$ ,  $a_3 = 2(1 - \pi B / f_s) \cos(\theta)$  and  $a_4 = -(1 - \pi B / f_s)^2$ , in which  $\theta = 2\pi f_{nom} / f_s$ , and  $B, C, f_{nom}, f_s$  are -3 dB response bandwidth (in Hz), center-frequency response, PLI frequency and sampling rate, respectively (McManus et al., 1993, apud Lynn, 1971).

In order to compare the proposed method with a classical approach, the recursive notch filter was selected. Lynn (1971) apud McManus et al., (1993), set  $B \approx 10$  Hz,  $C \approx 0.01$  and  $f_s = 1$  kHz. Such parameters do not assure the best results for the signals tested in this work. Therefore, they were empirically set as  $B = 5$  Hz,  $C = 0.005$  and  $f_s = 500$  Hz, assuring best results.

Considering that the objective of this work is to introduce a new method that overcomes the thresholding techniques, the results were compared to the ones obtained by a classical approach.

**Evaluation metrics**

In the literature, many objective measures are proposed to assess denoising techniques. One of them is the SNR, given by  $SNR = 10 \log_{10}(\sigma_x^2 / \sigma_y^2)$  dB where  $\sigma_x^2$  and  $\sigma_y^2$  are,

respectively, signal and noise variances. For a signal  $x(t)$ , the SNR improvement is defined by Awal et al. (2014) as  $SNR_{imp} = 10 \log_{10} \left[ \frac{\sum |s(t) - x(t)|^2}{\sum |\hat{x}(t) - x(t)|^2} \right]$  dB, where  $\hat{x}(t)$ ,  $s(t)$  and  $x(t)$  represents the denoised signal, noisy signal and original ECG signal, respectively. Another measure, associated with mean square error is the root mean square error (*RMSE*) expressed by  $RMSE = \sqrt{1/N \sum [\hat{x}(t) - x(t)]^2}$ , where  $N$  is the signal length. The relative error in the signal estimation can be written as  $\varepsilon = 1/N \sum |\hat{x}(t) - x(t)|$ . A statistical measure that allows the linear association between the predicted signal and the original one is the correlation coefficient (Üstündağ et al., 2012):  $r = \frac{\sum [x(t) - \mu_x][\hat{x}(t) - \mu_x]}{\sqrt{\sum [x(t) - \mu_x]^2 \sum [\hat{x}(t) - \mu_x]^2}}$ , where  $\mu_x$  and  $\mu_x$  are the expected values for  $x(t)$  and  $\hat{x}(t)$ , respectively. This measure varies from -1 to 1 and the zero means no linear relationship.

The measures presented before are appropriate for synthetic ECG signals, but not for real signals, since, in that case, there is no prior access to noiseless ECG signals samples. In this way, two metrics, proposed by Li et al. (2014), are used: the relative QRS complexes energy, given by  $eSQI = \sum E_r / E_a$ , and the relative standard deviation, given by  $stdSQI = (\sum \sigma_r) / 2M\sigma_a$ , where  $E_a$  is the energy of the whole signal,  $E_r$  is the energy in each QRS complex,  $M$  is the total number of

QRS complexes,  $\sigma_i$  is the standard deviation of each QRS complex and  $\sigma_{a_i}$  is the standard deviation around the  $i$ -th QRS complex (from:  $R - 0.2s$  to  $R + 0.2s$ ; where  $R$  is the location of each R peak).

### Statistical analysis

In order to evaluate whether the differences among the means in the experimental results are merely due to some random samples in the population, it is used the Kruskal-Wallis test. In this statistical test, ranks are used instead of the original observations. Firstly, all observations are ranked together and then the sum of the ranks is computed for each sample by means of the equation:  $H = \frac{12}{\sum n_i (\sum n_i + 1)} \sum_{i=1}^N \frac{R_i^2}{n_i} - 3(\sum n_i + 1)$  where  $N$  is the number of samples,  $n_i$  is the number of the observations and  $R_i$  is the sum of ranks in the  $i$ -th sample (Kruskal and Wallis, 1952).  $H$  corresponds to some value in the  $\chi^2$  distribution. Thus, the probability to get a highest or equal value than  $H$  is given by  $\Pr[\chi_{N-1}^2 \geq H]$ , that is named  $p$ -value, with  $N - 1$  degrees of freedom. When  $H$  is large and  $p$ -value  $\leq \alpha$ , then the null hypothesis is rejected (Kruskal and Wallis, 1952). In our case, the null hypothesis is that there is no significant difference among the tested methods. In this work  $\alpha = 0.05$ .

### Proposed method

According to equation (1), the ECG signal represented by  $s(t)$  is added to another signal which represents the PLI. Thus, an estimated ECG signal  $\hat{x}(t)$  can be obtained as follow:

$$\hat{x}(t) = s(t) - \alpha \cos(2\pi f_p t + \phi). \quad (9)$$

In the wavelet domain, the signal  $s(t)$  is represented by the approximation coefficients and PLI is contained in detail coefficients for a specific subband. Consequently, a simple approach to enhance the ECG signal in the wavelet domain is to reconstruct the signal  $\hat{x}(t)$  discarding detail coefficients. Based on the wavelet representation, Equation (8), the signal  $\hat{x}(t)$  can be written as a product comprising scaling functions and low-pass filter outputs added to the sum of the product of wavelet functions and high-pass filter outputs. In the  $j$ -th level, low-frequency components are limited in the interval  $[0, f_s / 2^{j+1}]$  while the high-frequency components are in interval  $[f_s / 2^{j+1}, f_s / 2^j]$ . Note that the precise frequency spectrum partition is impractical, since the filters frequency responses should be ideal (Peng et al., 2009). It results in a band overlap with frequency content close to  $f_s / 2^{j+1}$ . In the overlap band interval the energy leakage occurs when the wavelet decomposition is used (Peng et al., 2009), i.e., besides the expected frequency components, other frequencies also appear in the decomposed signal.

Peng et al. (2009) solved this problem by resampling the signal when the frequency content of interest is in the neighborhood of  $2^{-2} f_s$ .

Choosing  $f_s$  in a such a way that the approximation coefficients spectrum is limited in the range  $[0, 25.0]$  Hz and for detail coefficients spectrum is limited in the range  $[a, b]$ , where  $a \geq 25$  Hz and  $b \geq 60$  Hz, for some decomposition level  $j$ , and  $2^{-2} f_s > 25$  Hz, it is possible to separate, in the wavelet domain, the PLI noise from the corrupted ECG signal. Obviously, the choice of  $j$  depends on the ECG signal sampling rate  $f_s$ . According to Nyquist's Theorem,  $f_s$  should satisfy the following inequality:  $f_s \geq 2f_N$ , where  $f_N$  is the maximum frequency of the signal. For instance, if  $f_s = 125$  Hz then  $f_N = 62.5$  Hz, and therefore if  $j = 1$ , approximation coefficients are in the range  $[0, 31.25]$  Hz, which comprises the frequency range content in an ECG signal. Detail coefficients are in the range  $[31.25, 62.5]$  Hz, containing PLI noise and other high-frequency noises.

As suggested by Peng et al. (2009), the upper limit for the approximation coefficients is higher than 25 Hz, which is the frequency of interest. Therefore, setting the sampling rate at 125 Hz is suitable. Obviously, for other sampling rates that are integer multiple of 125 Hz, the ECG signal and PLI noise can also be separated, but for higher decomposition levels. Nevertheless, for the experiments performed in this work the best results were obtained at a sampling frequency of 500 Hz. In Table 4 it is shown the frequency distribution in each decomposition level for such sampling rate. Columns two and three show the frequency range for ideal cut-off frequencies according to the range shown in the Figure 1. Columns four and five show the real ranges, which are approximated values, obtained by analyzing the frequency response with the Symlet 8-tap. In the column six are presented the approximate band overlap ranges, considering the quadrature mirror analysis filters from Equations (4) and (5).

In a noise-free ECG signal reconstruction, detail coefficients are not so important, since they do not have relevant information about the ECG signal waveform, as shown in Table 4. Therefore, in order to obtain the signal  $\hat{x}(t)$ , given the sampling rate  $f_s$ , a decomposition level  $L \leq J$  must be chosen, where  $J$  is the maximum level. Afterward, it is assumed  $d_j[n] = 0$ , for all  $n$  and  $j = 1, 2, \dots, L$  in Equation (8). In this way, it follows from equation (8) that

$$\hat{x}(t) = \sum_n a_L[n] \phi_{L,n}(t). \quad (10)$$

The proposed method can be summarized in four steps: 1) The ECG signal is sampled at  $f_s = L \cdot 125$  Hz,  $L$  is a positive integer; 2)  $W / 2$  null samples are added to the signal edges, where  $W = 1000$  is the window length; 3) signal is split using a  $W$ -length Hanning window with an overlap of 50%; 4) for each window, next steps are

**Table 4.** Frequency distribution for the wavelet decomposition of a signal sampled at 500 Hz considering a 3 dB cut-off frequency, according to Figure 1.

Level	Ideal frequency range (Hz)		Real frequency range (Hz)		Band overlap range (Hz)
	Approximation	Detail	Approximation	Detail	
1	0-125	125-250	0-138.6	111.4-250	111.4-138.6
2	0-62.5	62.5-125	0-69.30	55.72-138.58	55.72-69.30
3	0-31.25	31.25-62.5	0-34.60	27.87-62.49	27.87-34.60

run; 4.1) DWT is applied to the splitted signal, up to the level  $L$ ; 4.2) set  $d_j[n]=0$  for all  $n$  and  $j=1,2,\dots,L$ ; 4.3) The estimated ECG signal is reconstructed according to equation (10).

The choice of the parameter  $L$  is the key to isolate the noise in a wavelet decomposition subband and that is why the sampling rate was defined as multiple of 125 Hz. If such sampling rate is not possible, there is no guarantee that the PLI will appear in the detail coefficients. In this way, resampling of the ECG signal should be considered. The null samples are added to avoid abrupt changes in the signal ends and  $W/2$  samples are necessary due to the window overlap, which is an important procedure in signal processing. Generally, the window overlap vary from 50% to 75% (Prabhu, 2014), but for the proposed method better results were achieved with 50% overlapping.

## Results

### The wavelet function choice

When applying the wavelet transform, besides the decomposition level choice discussed in the last section, it is also important to choose the wavelet function that best fits the signal. When ECG is the subject and threshold based methods are used, some researchers prefer Symlet wavelets because their scaling function resembles more its waveform (Awal et al., 2014; Chouakri et al., 2006; Karthikeyan et al., 2012; Li et al., 2009). Good results are also found using Daubechies wavelets (Karthikeyan et al., 2012; Patil and Chavan, 2012; Üstündağ et al., 2012) and Coiflet (Agante and Sa, 1999; Karthikeyan et al., 2012). On the other hand, Poornachandra and Kumaravel (2008) compared some wavelet families with Mayer's wavelet and conclude that the last one is better. Commonly, each method uses different thresholding techniques and they have influence on the wavelet function choice. However, there is some agreement about the use of Daubechies and Symlet wavelets. As the proposed method does not use thresholding techniques, the choice of wavelet function can be made by analyzing the results of experiments using the synthetic signals from Table 1 and Table 2. Preliminary experiments with the proposed method showed that the relative error obtained when using Symlets is smaller than the one using Daubechies wavelet functions. Furthermore, it was noted that higher

wavelet order leads to better result. However, runtime increases substantially.

For instance, the difference between the relative errors metrics, for the synthetic signal  $s_1$ , using sym10 (Symlet wavelet function of order 10) and sym20 is  $5.14 \times 10^{-4}$  and the absolute difference between runtimes is around  $2.17 \times 10^{-2}$  seconds. When  $s_{15}$  is considered, which is the one with worse SNR, runtime increases by about  $10^{-3}$  seconds, from sym2 to sym8. From sym8 on, this metric increases by an amount of  $10^{-1}$  seconds when the number of the wavelet vanishing moments increases. On the other hand, the relative error metric decreases in average  $2 \times 10^{-4}$  for each new Symlet wavelet function order, from sym4 on. Longer runtime is due to higher amount of the filters coefficients for wavelets of higher order.

Figure 2 shows the boxplots of the experiments for denoising synthetic signals with worse SNR:  $s_6, s_8, s_{11}, s_{12}, s_{13}, s_{15}, s_{16}, s_{17}$  and  $s_{20}$ . Each box displays the relative error and runtime for different Symlet wavelet orders. The higher the order of the wavelet, the larger the filter length and number of the vanishing moments. This implies on softer functions and higher runtime. In general, the relative error remains almost constant from sym8 on, according to the results presented. Conversely, runtime is almost constant for wavelet functions with order lower than 8, increasing significantly after sym8. Therefore, considering balance between the relative error and the runtime, the authors believe that the best results could be achieved using sym8.

### Experiments

In order to validate the proposed method, evaluation measures were computed for each synthetic signal. According to the analysis in last section, Symlet 8 was used for simulations. Superscripts PM, TT and NF refer to proposed method, thresholding technique and notch filter, respectively.

Analyzing column eight in Table 5, it can be seen a significant  $SNR_{imp}$  when compared to the values from row two in Table 1 and Table 2. For  $s_{15}$  signal, with input  $SNR$  around  $-30$  dB, the improvement was 50.9574 dB.  $s_{11}$ , with input  $SNR$  around  $-26$  dB, the second worse, has an improvement of 45.8751 dB. In a general view, the  $SNR_{imp}$  metric has an average close to 40.7806 dB. The correlation coefficient  $r$  (eleventh



column) is close to one for all signals, meaning that the estimated signal waveform matches with the original ECG signal. Relative error  $\varepsilon$  and  $RMSE$  metrics indicate an accuracy of at least  $10^{-2}$  for almost all experiments.

In Figure 3, one can see the results in time and frequency domain, when applying the denoising methods for signal  $s_{15}$ .

Table 6 shows results obtained by the proposed method, thresholding technique and notch filter for real signals. Comparing the original values in fourth column of Table 3 with the ones from the eighth to the tenth columns of Table 6, it is noted that the frequencies over 25 Hz are less relevant for the denoised ECG signal than in the noisy ECG for all analyzed signals.

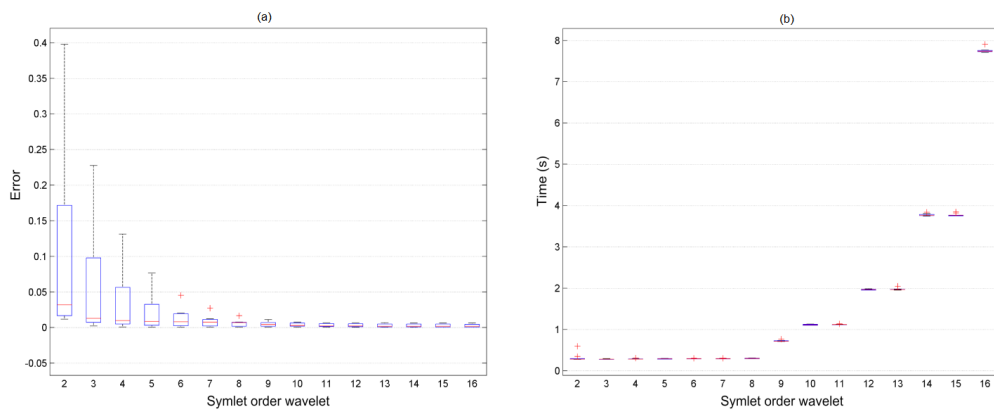
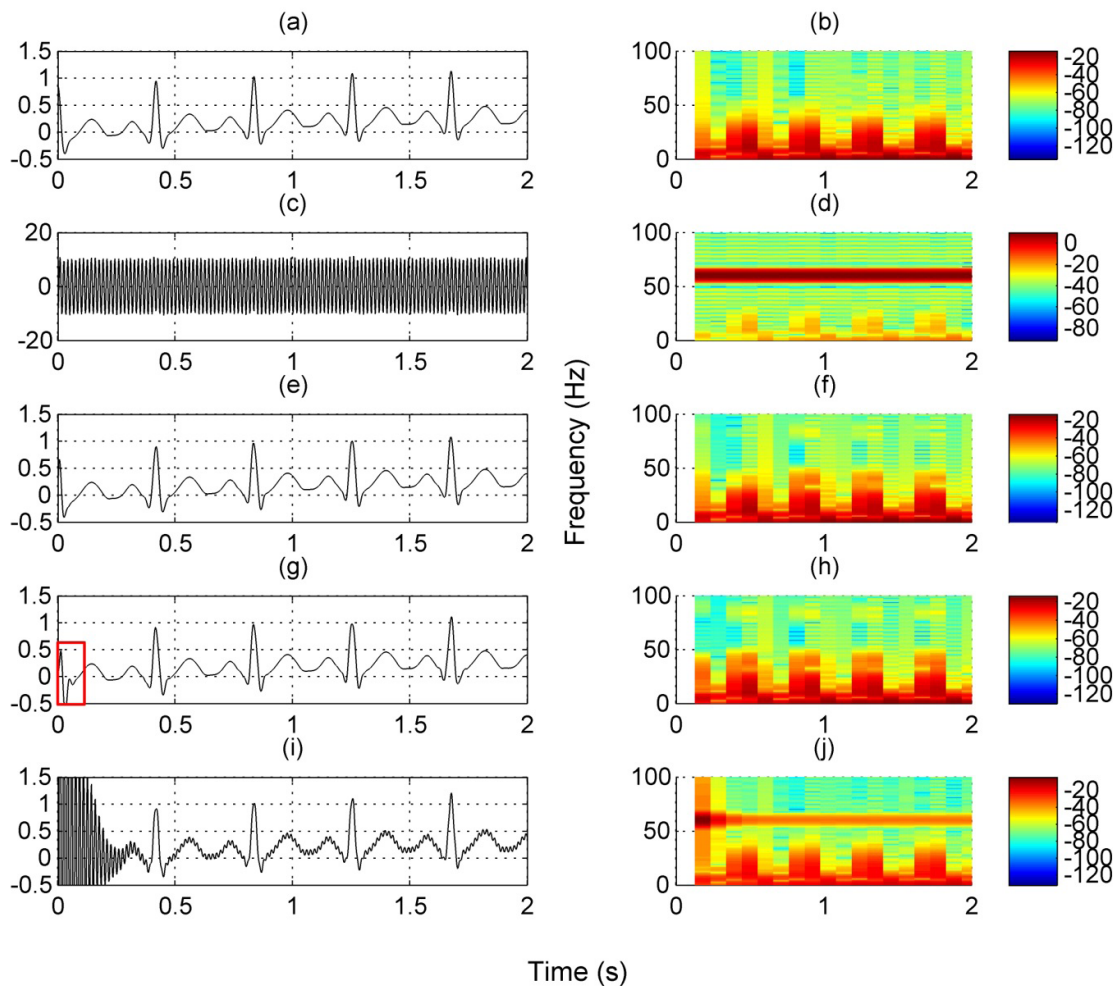


Figure 2. Boxplot for several Symlet wavelet orders: (a) relative error metrics boxplot, (b) runtime.

Table 5. Results for the proposed method (PM), thresholding technique (TT) and notch filter (NF) applied to synthetic ECG signal.

Signal	$RMSE^{PM}$	$RMSE^{TT}$	$RMSE^{NF}$	$SNR_{imp}^{PM}$	$SNR_{imp}^{TT}$	$SNR_{imp}^{NF}$	$r^{PM}$	$r^{TT}$	$r^{NF}$
$s_1$	<b>0.0075</b>	0.0098	0.0189	<b>39.5135</b>	37.1723	31.4736	<b>0.9994</b>	0.9991	0.9972
$s_2$	<b>0.0080</b>	0.0103	0.0149	<b>35.8650</b>	33.6532	30.4104	<b>0.9995</b>	0.9991	0.9988
$s_3$	0.0049	<b>0.0018</b>	0.0086	29.1643	<b>38.0101</b>	24.3344	0.9997	<b>1.0000</b>	0.9998
$s_4$	<b>0.0040</b>	0.0053	0.0094	<b>36.9897</b>	34.5251	29.5679	<b>0.9998</b>	0.9996	0.9991
$s_5$	<b>0.0075</b>	0.0103	0.0099	<b>19.4379</b>	16.7149	17.0817	<b>0.9995</b>	0.9991	0.9997
$s_6$	<b>0.0190</b>	0.0292	0.0474	<b>40.0431</b>	36.3182	32.1079	<b>0.9963</b>	0.9913	0.9802
$s_7$	0.0062	<b>0.0015</b>	0.0143	37.9753	<b>50.1589</b>	30.7739	0.9997	<b>1.0000</b>	0.9989
$s_8$	0.0148	<b>0.0059</b>	0.0228	35.1591	<b>43.2127</b>	31.4330	0.9979	<b>0.9997</b>	0.9972
$s_9$	<b>0.0043</b>	0.0048	0.0100	<b>33.8243</b>	32.8589	26.4913	0.9998	<b>0.9998</b>	0.9996
$s_{10}$	<b>0.0067</b>	0.0088	0.0281	<b>44.0353</b>	41.6684	31.5227	<b>0.9996</b>	0.9993	0.9941
$s_{11}$	<b>0.0259</b>	0.0472	0.1282	<b>45.8751</b>	40.6579	31.9784	<b>0.9941</b>	0.9809	0.8867
$s_{12}$	<b>0.0060</b>	0.0152	0.0986	<b>56.7105</b>	48.6041	32.3823	<b>0.9997</b>	0.9980	0.9306
$s_{13}$	0.0100	<b>0.0003</b>	0.0105	35.0189	<b>65.0196</b>	34.6267	0.9992	<b>1.0000</b>	0.9998
$s_{14}$	<b>0.0089</b>	0.0113	0.0265	<b>40.9507</b>	38.8206	31.4428	<b>0.9993</b>	0.9989	0.9949
$s_{15}$	<b>0.0208</b>	0.0371	0.1793	<b>50.9574</b>	45.9358	32.2579	<b>0.9955</b>	0.9859	0.7850
$s_{16}$	<b>0.0125</b>	0.0207	0.0589	<b>45.3992</b>	41.0428	31.9638	<b>0.9982</b>	0.9951	0.9655
$s_{17}$	0.0056	<b>0.0010</b>	0.0375	50.6373	<b>65.5897</b>	34.1308	0.9997	<b>1.0000</b>	0.9891
$s_{18}$	<b>0.0245</b>	0.0312	0.1182	<b>45.9789</b>	43.8886	32.3125	<b>0.9950</b>	0.9920	0.9065
$s_{19}$	<b>0.0122</b>	0.0385	0.0806	<b>48.6787</b>	38.7278	32.3051	<b>0.9978</b>	0.9788	0.9204
$s_{20}$	<b>0.0148</b>	0.0304	0.0534	<b>43.3985</b>	37.1499	32.2712	<b>0.9969</b>	0.9870	0.9646
Average	<b>0.0112 ± 0.0065</b>	0.0160 ± 0.0140	0.0488 ± 0.0471	40.7806 ± 8.2487	<b>41.4865 ± 10.4377</b>	30.5434 ± 3.8225	<b>0.9983 ± 0.0017</b>	0.9952 ± 0.0066	0.9654 ± 0.0538
$H$		14.704			27.927			8.2435	
$p$ -value		0.0006			0.0000			0.0162	



**Figure 3.** Analysis display for signal  $s_{15}$ . (a) Synthetic ECG signal and (b) its spectrogram. (c) Noisy ECG signal and (d) its spectrogram. Denoised ECG signals obtained by (e) proposed method, (g) thresholding technique and (i) notch filter, and their spectrograms (f), (h) and (j), respectively. The red rectangle highlights a distortion inserted by the thresholding technique.

**Table 6.** Results for the proposed method, thresholding technique and notch filter applied to real ECG signals. PSD column is the sum of the power spectrum density for frequencies over 25 Hz.

Record (Lead)	$eSQI^{PM}$	$eSQI^{TT}$	$eSQI^{NF}$	$stdSQI^{PM}$	$stdSQI^{TT}$	$stdSQI^{NF}$	$PSD^{PM}$	$PSD^{TT}$	$PSD^{NF}$
1007823 (II)	<b>0.650</b>	0.647	0.645	<b>0.208</b>	0.207	0.204	<b>-2.771</b>	-2.301	-1.556
1034914 (III)	<b>0.448</b>	0.442	0.428	<b>0.192</b>	0.192	0.192	<b>-3.531</b>	-2.243	-1.237
1086219 (III)	0.393	<b>0.404</b>	0.396	<b>0.214</b>	0.214	0.214	<b>-2.716</b>	-2.056	-1.326
1098605 (V1)	<b>0.468</b>	0.460	0.453	<b>0.340</b>	0.340	0.300	<b>-3.425</b>	-2.085	-1.397
1105115 (V2)	<b>0.428</b>	0.418	0.500	<b>0.785</b>	0.135	0.131	<b>-57.92</b>	-38.16	2.681
1124627 (aVL)	<b>0.543</b>	0.530	0.529	<b>0.168</b>	0.168	0.168	<b>-2.200</b>	-1.988	-1.088
2209843 (I)	<b>0.676</b>	0.608	0.430	<b>0.331</b>	0.330	0.330	<b>-3.460</b>	-1.779	-1.261
1138505 (I)	<b>0.438</b>	0.434	0.602	0.263	<b>0.264</b>	0.263	<b>-2.760</b>	-1.922	-1.573
Average	<b>0.506±0.099</b>	0.493±0.085	0.062±0.083	<b>0.313±0.187</b>	0.233±0.069	0.028±0.063	<b>-2.649±18.175</b>	-1.749±11.944	-0.143±1.341
<i>H</i>		0.1350			1.4982			18.005	
<i>p</i> -value		0.9347			0.4728			0.0001	

## Discussion

Comparing the proposed method results to the ones obtained with hard thresholding method, it can be seen that the proposed method was worse than hard thresholding only for  $s_3$ ,  $s_7$ ,  $s_8$ ,  $s_{13}$  and  $s_{17}$  signals. In fact, the proposed method performed better in all requirements for all other signals. Average values reaffirm that the proposed method was better for the most of the evaluation measurements, except in terms of  $SNR_{imp}$ . However, the differences on  $SNR_{imp}$  values were not significant. For this metric, the proposed method was better than thresholding technique for 75% of the synthetic signals. In addition, it got higher results for signals  $s_{11}$  and  $s_{15}$ , the ones with the worst  $SNR$  values.

By means of the Kruskal-Wallis test, we conclude that there exists significantly statistical difference for at least two methods. In comparison to notch filter, the proposed method was better for all measures. However, the proposed method and the thresholding technique have a similar performance in statistical terms.

Note, from Figure 3 (f), that the energy of the QRS complexes remains practically unchanged when compared to the original. The original signal energy is close to  $3.2015 \times 10^3$ , whereas the energy of the denoised ECG signals obtained by the proposed method, thresholding technique and notch filter, are close to  $3.2188 \times 10^3$ ,  $3.3894 \times 10^3$  and  $12.6194 \times 10^3$ , respectively. In addition, note from Figure 3 (g), that the thresholding technique inserted a distortion in the initial samples of the ECG signal whereas the proposed method did not change its waveform. Moreover, it can be seen from Figure 3, (i) and (j), that notch filter achieved poor performance, since PLI was only attenuated. In the signal first samples it cleared the PLI with biggest gain. This outcome is common for notch filter (Nauman et al., 2013). Due to the fact that some ECG analysis is performed by humans, a good visual quality is essential for an accurate diagnosis. Thus, one can conclude that the proposed method performed the best in terms of noise attenuation and distortion insertion.

For real ECG signals, from Table 6, it is notorious that the proposed method reached better results for all signals, except for record 1086219 with respect to  $eSQI$  and record 1138505 for  $stdSQI$ . It is still noticeable that  $eSQI$  measure values are greater for signals obtained by the proposed method than the ones for the original signals. Since this measure is directly proportional to the QRS complex energy, these results mean that the high frequency noises (60 Hz or 50 Hz) have their gain attenuated. Furthermore, the proposed method performed the best for most of ECG signals, and it is important to highlight that its computational complexity is lower, since the additional thresholding technique complexity due to threshold computation is  $O(N)$  (Lang et al., 1996).

In comparison to notch filter, the proposed method obtained better results for all signals. It is noteworthy that notch filter performed the worst for all quality assessment tests.

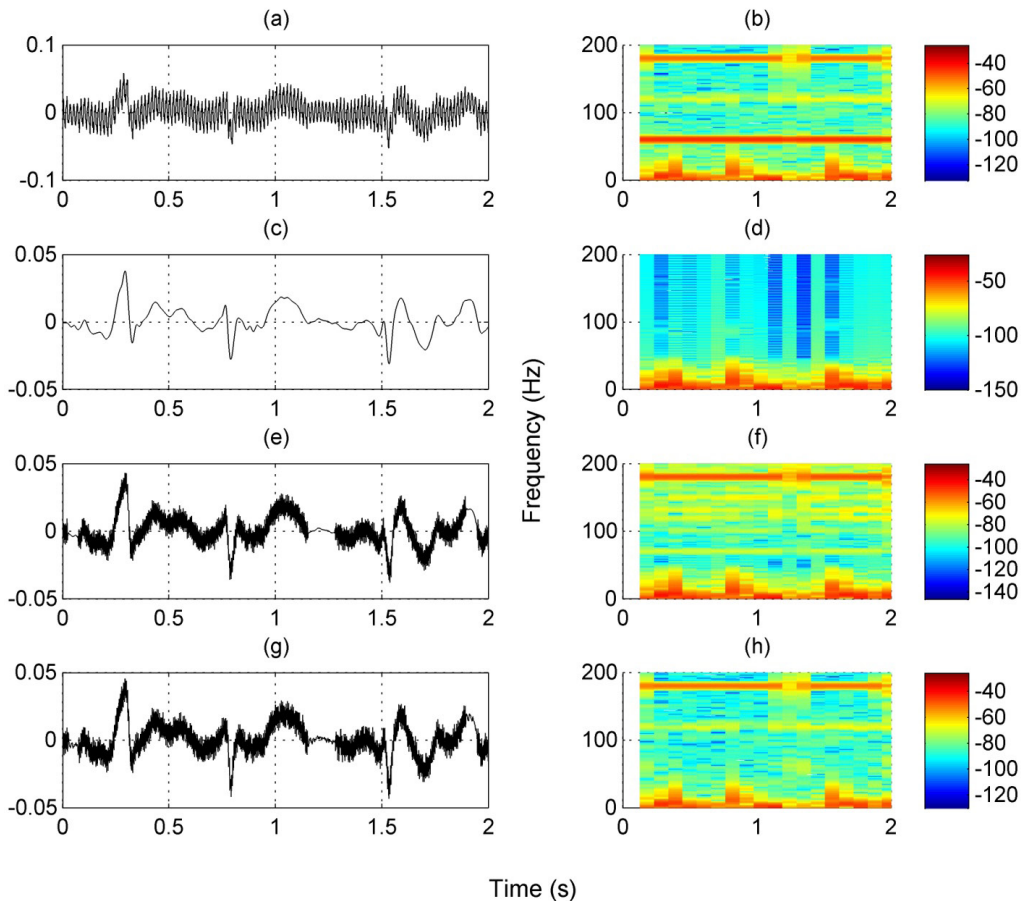
From Kruskal-Wallis test results, it is noted that only for the  $PSD$  measure there are significantly statistical difference among the three methods, considering a level of significance of  $\alpha = 5\%$ . This is because the other measures not consider the PLI noise.

From Figure 4, one can observe that thresholding technique and notch filter removed the PLI only for some segments in the observed ECG signal, leaving the others attenuated. Hereby, the result for record 1105115 obtained by the proposed method is much better (Table 6, fifth row) than the other methods, since the high frequency noise (180 Hz, see spectrogram in Figure 4) was not removed by the thresholding technique and notch filter. Note that 180 Hz is 2-nd harmonic frequency of 60 Hz.

Although the proposed method have obtained better results for the most of the analyzed signals, it is important to note that it depends on ECG signals sampling rate. So, one must be careful on the sampling rate and DWT decomposition level choices, since these parameters have great influence in the estimated signals quality, according to steps 1 and 4.2 of the proposed method. When, by technical reasons, the sampling rate cannot be changed, decomposition level must be chosen in such a way that a minimum amount of noise crosses into the signal subband.

Other limitation of the proposed method refers to the frequency content removed. In a scenario where frequencies over 34.60 Hz (see Table 4) are relevant, detail coefficients in the first level can be retained (frequencies in the range 111.40 to 250 Hz). Even so, PLI noise is removed. Though, in any case, the frequency content around 50/60 Hz is lost. In this way, the cardiac disorders that generate frequencies into the interval from 34.60 to 111.40 Hz are despised. It is essential to note that bandwidth mentioned in Table 4 can be distinct, provided that other cut-off frequency is considered. Therefore, the frequencies higher than 34.60 Hz are preserved in the reconstructed ECG signal.

In overview, in this paper it was proposed a new method for PLI noise removal based on the wavelet transform without the use of thresholding techniques. For such purpose, it was used a filter bank architecture implemented by the multiresolution analysis that allows splitting a signal in frequency subbands. By setting the sampling rate in 500 Hz, it is possible to separate PLI noise from ECG signal in distinct frequency subbands by using the wavelet representation. In order to choose this sampling rate, the energy leakage was considered, such that, for a DWT decomposition level, the frequency content of interest was close to half of the maximum signal



**Figure 4.** (a) Raw ECG record 1105115 and (b) its spectrogram. Denoised ECG signal obtained by (c) proposed method, (e) thresholding technique and (g) notch filter and their spectrograms (d), (f) and (h), respectively.

frequency. Therefore, by zeroing detail coefficients, the ECG signal is reconstructed using only the approximation coefficients, obtaining a denoised ECG.

Energy conservation analysis for each cardiac cycle showed that the proposed method does not insert distortion in the estimated ECG signals. For real ECG signals, it was noted that the estimated QRS complexes waveforms are smooth and keep the expected morphology. On the other side, the thresholding technique added abrupt changes in some QRS complexes for records 1086219 and 2209843. Besides, other advantage of the proposed method is that there is no computational requirement for a threshold computation.

Although the proposed method depends on the sampling rate, it can be applied to other databases, with sampling rates different from a multiple of 125 Hz, since the signals resampling are considered. Finally, the proposed method can be applied for denoising other signals, with frequency content known in a specific range. In future works such applications will be considered.

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